



A Multiobjective, Multidisciplinary Design Optimization Methodology for the Conceptual Design of Distributed Satellite Systems

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Motivation



- **Objective:** To develop a **methodology** for mathematically modeling the **Distributed Satellite System (DSS) conceptual design** problem as an **optimization** problem to enable an efficient search for the best families of solutions within the system trade space.
- **Motivation:**
 - The trade-space for DSS's is **enormous** - too large to enumerate, analyze, and compare all possible system architectures.
 - MDO techniques have been applied successfully across many fields to find the solutions to **complex** problems.
 - "... the conceptual space systems design process is very **unstructured** ... designers often pursue a **single** design concept, patching and repairing their original idea rather than generating new alternatives." - Proceedings of the 1998 IEEE Aerospace Conference
 - A design that is **globally** optimized on the basis of a system metric(s) is likely to vary drastically from a design that has been developed by optimizing each **subsystem**.
 - A methodology is needed that will enable a greater search of the trade space and explore design options that might not otherwise be considered during the **Conceptual Design** Phase (when **lifecycle cost** gets locked in).

Case Studies



- **Name:** Terrestrial Planet Finder
- **Mission:** Terrestrial Planet Detection/
Characterization
- **Sector:** Civil
- **Sponsor:** NASA
- **TS Size:** 640 Architectures

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[Beichman et al, 1999]

- **Name:** TechSat 21
- **Mission:** Ground Moving Target
Indicator (GMTI)
- **Sector:** Military
- **Sponsor:** AFRL
- **TS Size:** 732,160

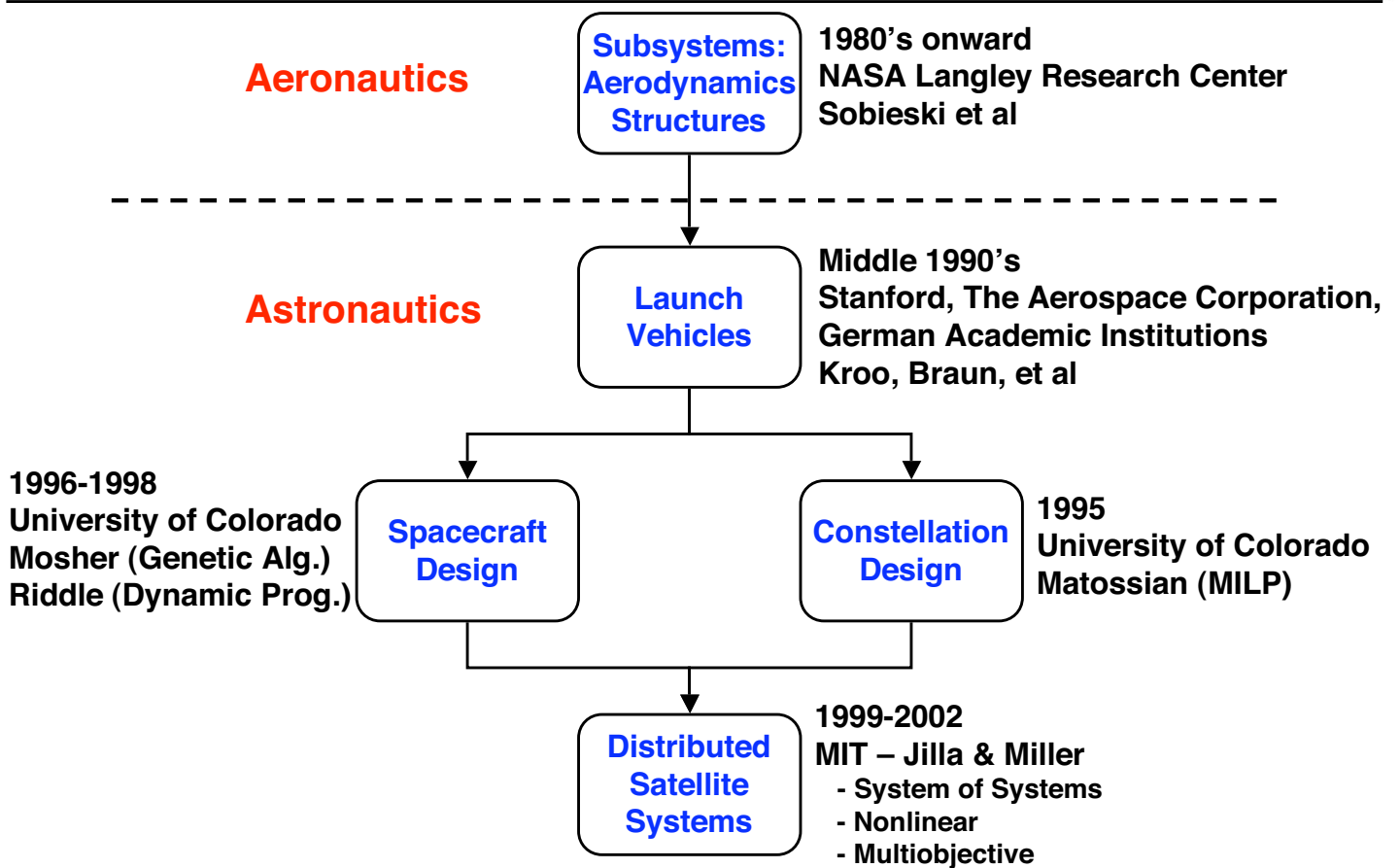
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- **Name:** [Martin, 2000]
Broadband Communication
- **Mission:** High Data Rate
Communication Services
- **Sector:** Commercial
- **Sponsor:** Private Company
- **TS Size:** 42,400 Architectures

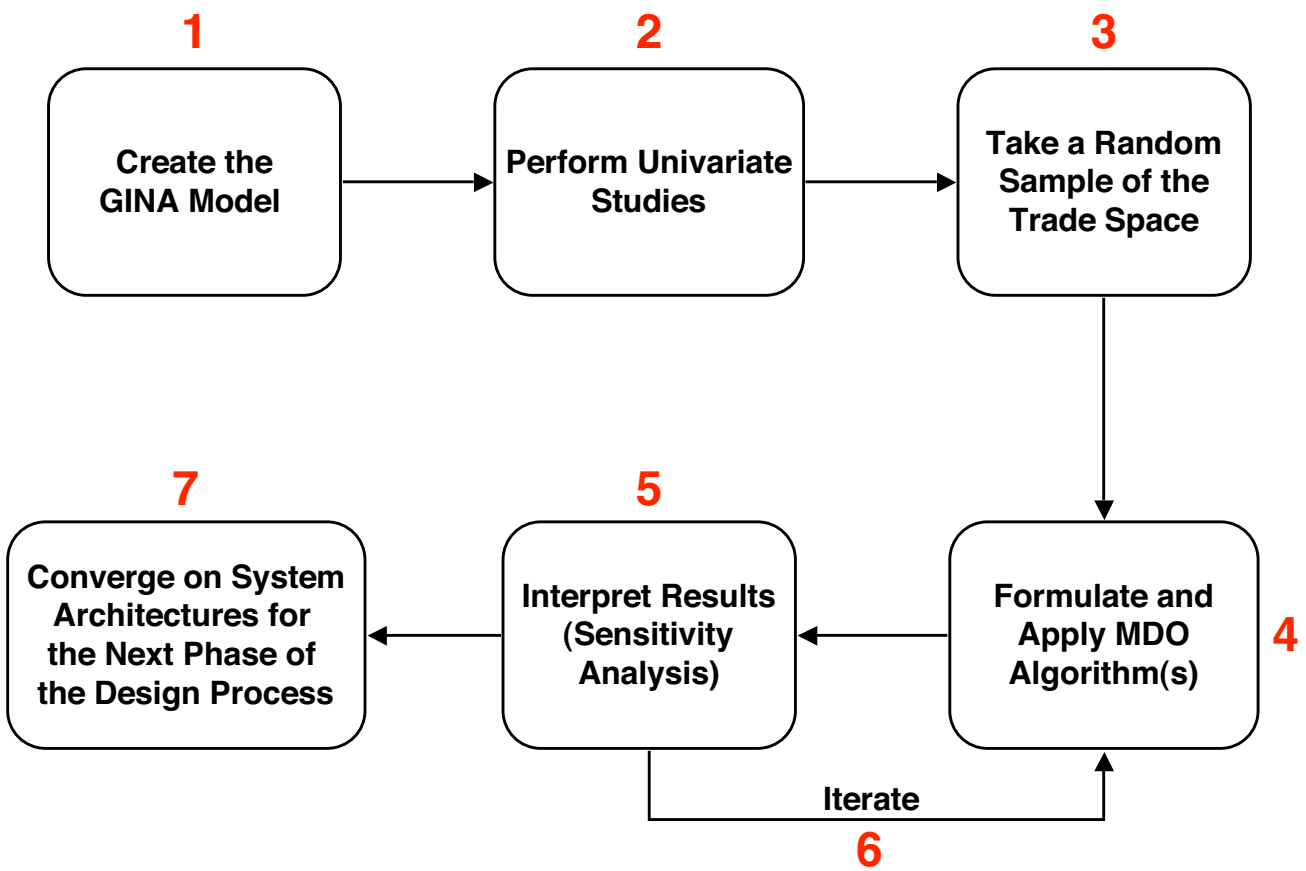
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[Boeing, 2002]

Past Work – Literature Review



The MMDOSA Methodology



Step 1 – Create the GINA Model



Top Trades Capability Metrics	Number of Satellites Per Cluster	Number of Clusters	Altitude	Aperture Diameter	Transmission Power
Isolation	N/A	N/A	MDV and maximum cluster baseline	N/A	N/A
Rate	N/A	Minimum revisit time	Revisit time and area search rate	Footprint coverage area	Required dwell time
Integrity	Antenna gain pattern from cluster projection	N/A	Received signal strength	Mainlobe vs. sidelobe gain	Impacts the signal-to- noise ratio
Availability	Overall system reliability	Overall system reliability	N/A	N/A	Time required to scan a target area
Cost per Function	Learning curve effects	Learning curve effects	Launch, eclipse, & drag	Antenna mass & cost	Size of spacecraft

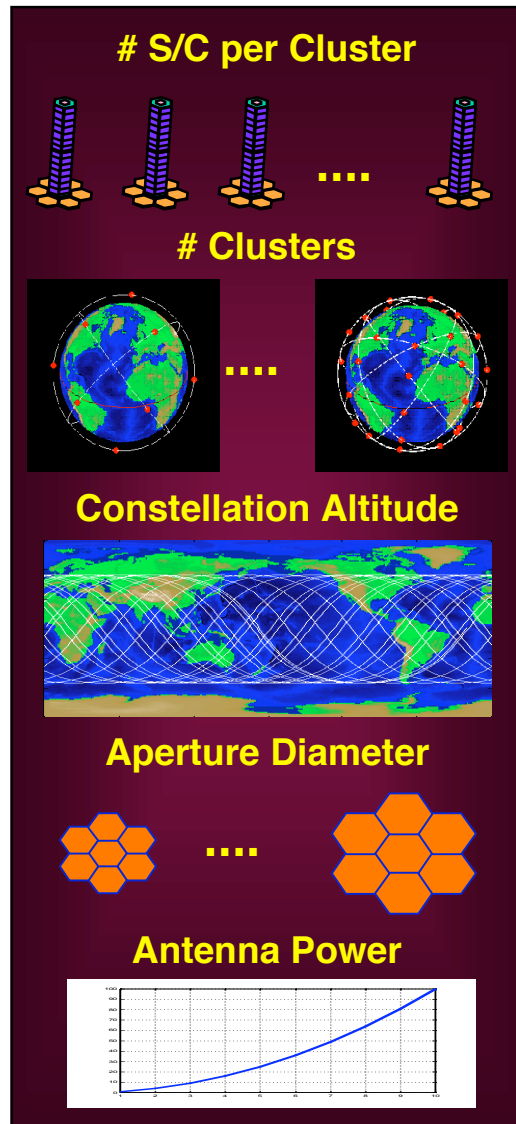
Constellation
 Radar
 Payload
 S/C Bus
 Deploy/Ops
 System Analysis

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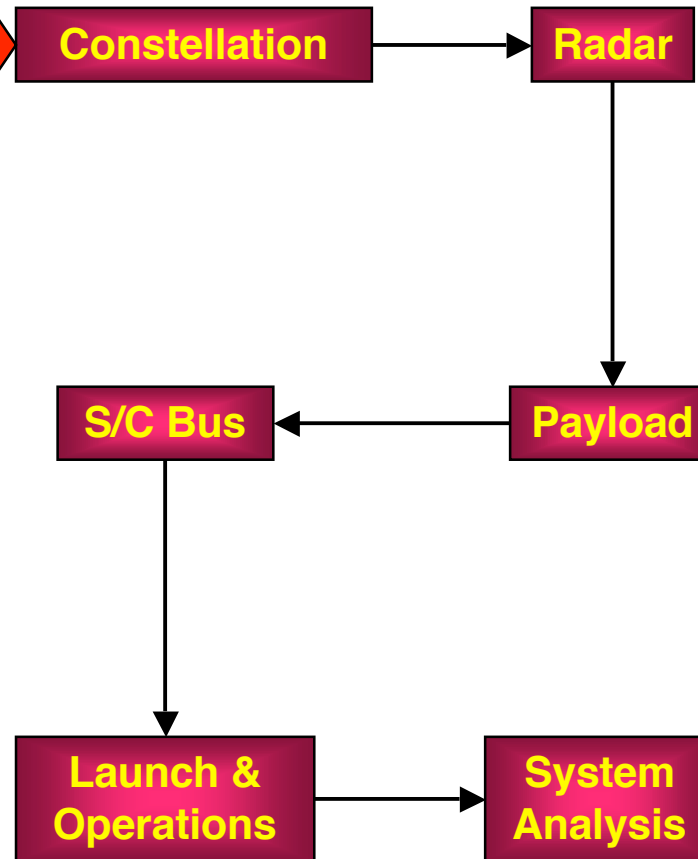
Step 1 – Develop Simulation Software



Inputs (Design Vector)



MATLAB Models



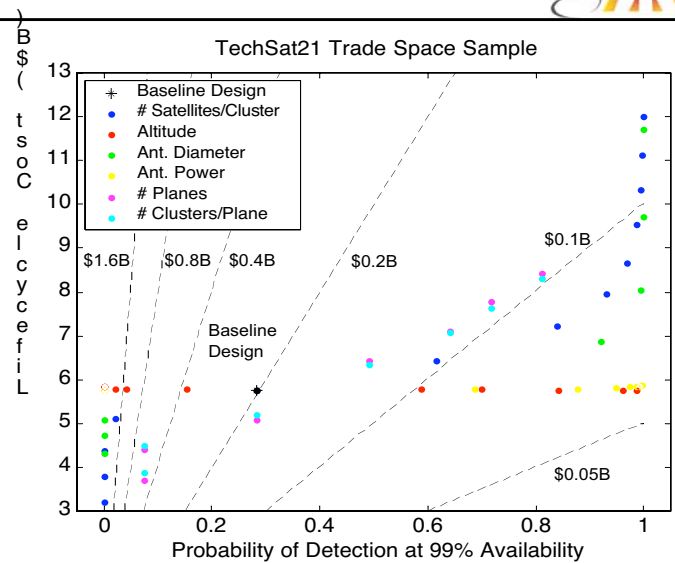
Key Outputs



Step 2 – Perform Univariate Studies



- Univariate Studies**
 - Select a baseline Γ . Holding everything else constant, **vary an individual γ_i** over its entire range of values and observe how the system attributes vary.
- Strengths**
 - Provides the systems engineer with an **initial feel** of the trade space.
 - Further assessment of **model fidelity**.
- Weaknesses**
 - Ignores couplings** between elements of the design vector.
 - Focuses on only a **local** portion of the global trade space.



- * Family Baseline Design Vector**
 - # Satellites Per Cluster: 8
 - Aperture Diameter: 2 m
 - Radar Transmission Power: 300 W
 - Constellation Altitude: 1000 km
 - # Clusters Per Orbital Plane: 6
 - # Orbital Planes: 6

Step 3 – Random Sample



- Random Sampling**

- Collecting and deriving data on a population (i.e. the complete set of architectures in the DSS global trade space) after measuring only a small subset of the population in such a way that every architecture in the trade space is **equally likely** to be selected.

- 95% Confidence Intervals**

- “Average” vs. $\sqrt{\quad}$ Optimized Designs

- Initial Optimization Bounds**

- LP Relaxation Analogy

- Gather Data to be Used Downstream to Tailor MDO Algorithms**

- Simulated Annealing Δ Parameter

TPF Random Sample (n=48)

Parameter	Lifecycle Cost (\$B)	Performance (# Images)	Cost Per Image (\$K)
Maximum	2.11	3839	2429
Minimum	0.74	390	474
Range	1.37	3449	4955
Mean	1.23	1681	849
Standard Deviation	0.30	731	367

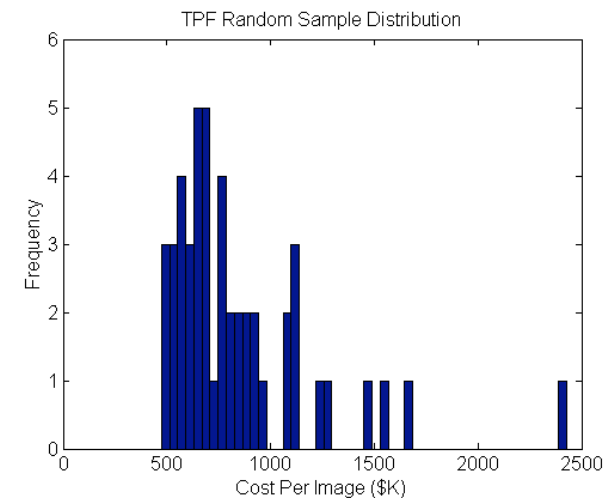
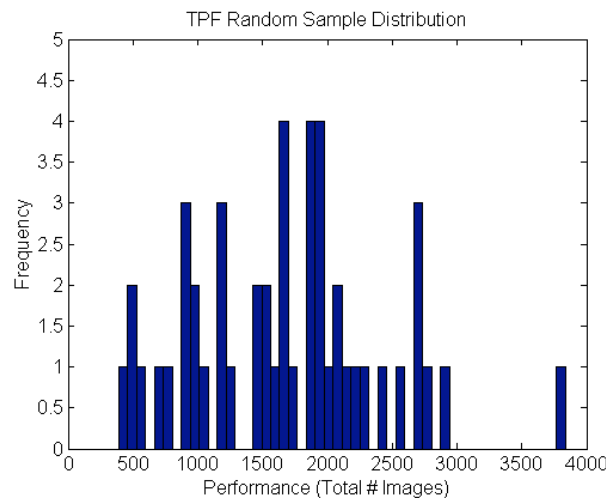
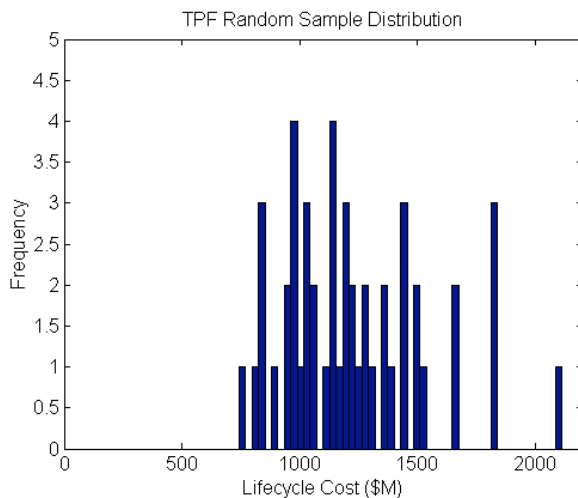


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Step 4 – Apply MDO Algorithms: Single Objective Optimization



- Application of **4 MDO Techniques**
 - Taguchi Methods
 - Simulated Annealing
 - Pseudo-Gradient Search
 - Univariate Search
- **Heuristic techniques** found to be the least susceptible to getting stuck in the local optima present in the trade space of DSS's.
- **Simulated Annealing** forms the core algorithm within MMDOSA.

MDO Technique Performance

Trial	Simulated Annealing (\$K/Image)	Pseudo-Gradient Search (\$K/Image)	Univariate Algorithm (\$K/Image)
1	493.8	470.8	469.6
2	470.0	470.0	469.6
3	469.6	469.6	513.8
4	505.1	520.9	469.6
5	470.8	469.6	526.0
6	470.8	469.6	513.8
7	493.8	532.6	470.8
8	470.0	469.6	525.9
9	498.2	470.8	469.6
10	496.4	483.0	473.9
MSE (\$K/Image)² (*)	397.1	678.3	1027.8

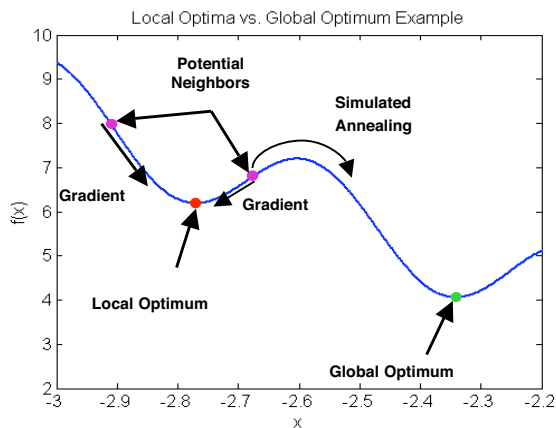
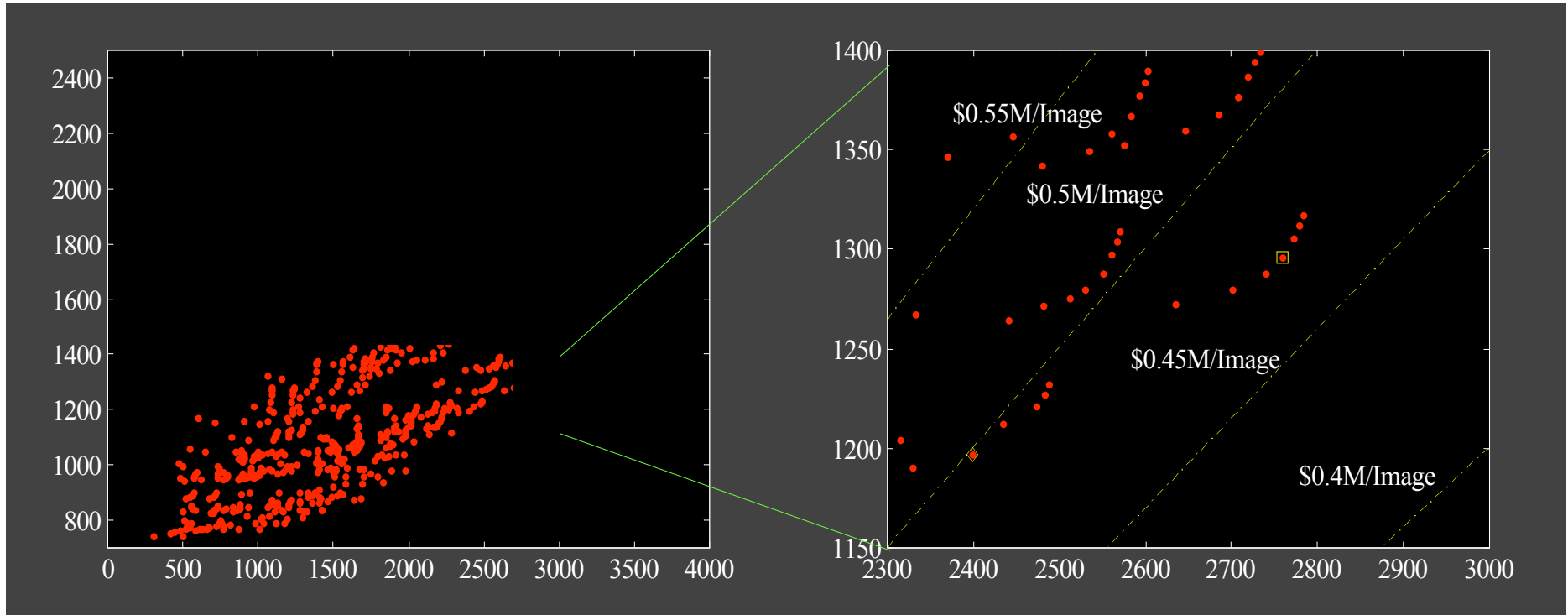


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Step 4 – Apply MDO Algorithms: Single Objective Optimization



“Optimal” Solution

Orbit **4 AU**
Interf. **SCI-2D**
Apert. **8**
Apert. **4 m**

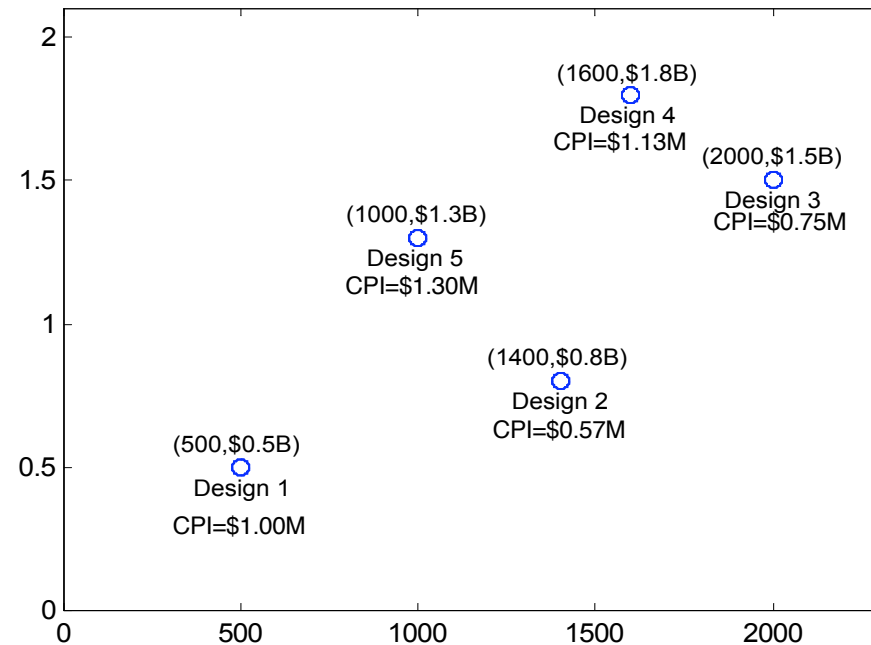
Number of Images **2759**
Total Cost **\$1.3 Billion**
Cost Per Image **\$469,000**

Step 4 – Apply MDO Algorithms: Multiobjective Optimization



- **Motivation:** True systems methods handles **trades**, not just a single metric. In real-world systems engineering problems, one has to **balance** multiple requirements while simultaneously trying to achieve **multiple** goals.
- **Differences** between single objective and multiobjective problems.
 - **Single objective** problems have only **one** true solution.
 - **Multiobjective** problems can have **more than one solution**.
- **Terminology:**
 - Dominated Solutions
 - Non-Dominated Solutions
 - Pareto Optimal Set

$$O_j(x_i) < O_j(y) \text{ for all } i \text{ and } j$$



Step 4 – Apply MDO Algorithms: Multiobjective Multiple Solution Algorithm



Pareto Front

Goal:

To find multiple architectures in the Pareto optimal set.

New Decision Logic

IF $E_n(\tilde{A}_k) < E_n(\tilde{A}_i)$ for ALL $n = 1, 2, \dots, N$
 $\tilde{A}_i \notin P$ $k = 1, 2, \dots, K, i-1$

ELSE

$\tilde{A}_i \in P$

END

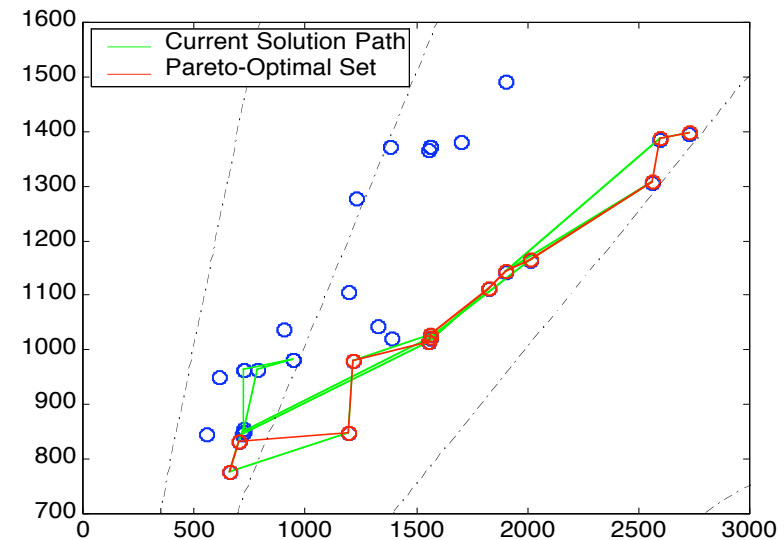
IF $\tilde{A}_{i+1} \in P$ OR $\chi < e^{-\frac{\Delta}{T}}$

$\tilde{A}_b = \tilde{A}_{i+1}$

ELSE

$\tilde{A}_b = \tilde{A}_i$

END



Observations:

- Along this boundary, the systems engineer cannot improve the **performance** of the design without also increasing lifecycle **cost**.
- This boundary **quantitatively** captures the **trades** between the DSS design criteria.

Step 4 – Apply MDO Algorithms: Approximating the Global Pareto Boundary

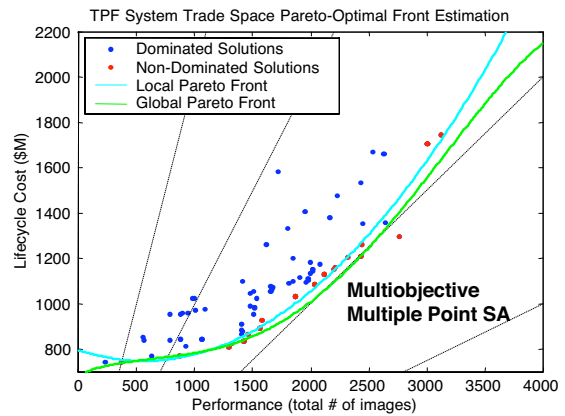
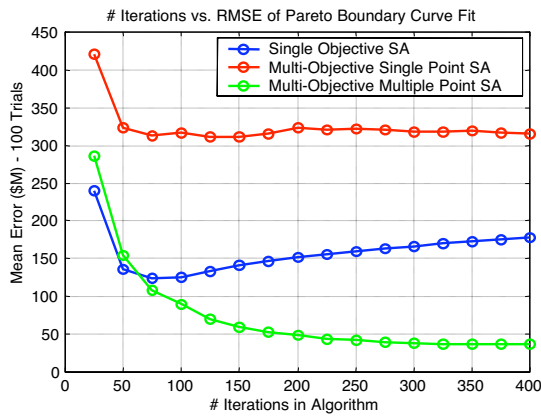
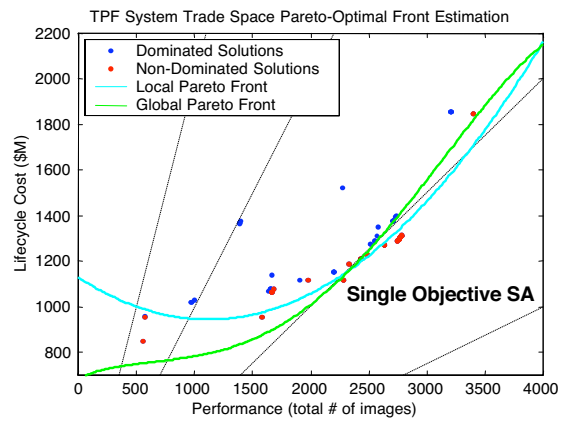
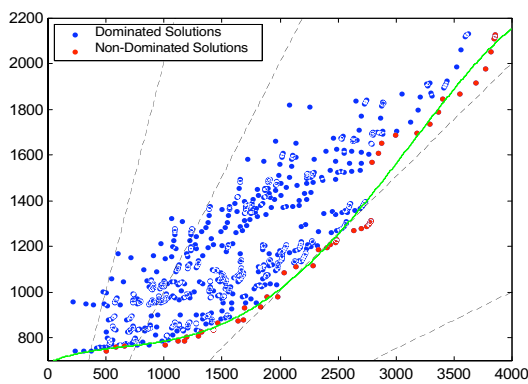
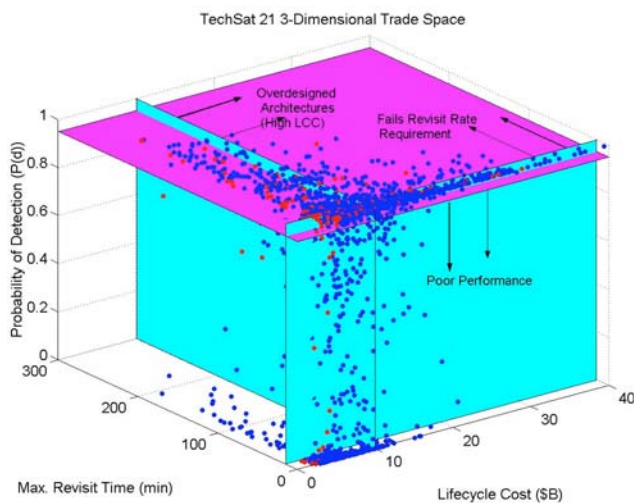


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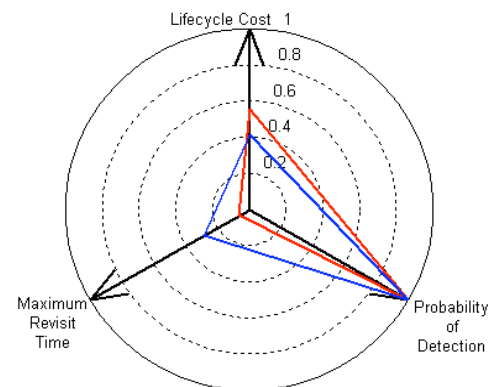
Step 4 – Apply MDO Algorithms: Multiobjective Optimization



- In a **two-dimensional trade space**, the Pareto Optimal set represents the **boundary** of the most design efficient solutions.
- The same principles of Pareto Optimality hold for a trade space with **any number n dimensions** (ie. any number of decision criteria).
- **3 Criteria Example for Space-Based Radar**
 - Minimize(Lifecycle Cost) AND
 - Minimize(Maximum Revisit Time) AND
 - Maximize(Target Probability of Detection)



Multi-Dimensional Comparison of 2 Pareto-Optimal TechSat21 Designs

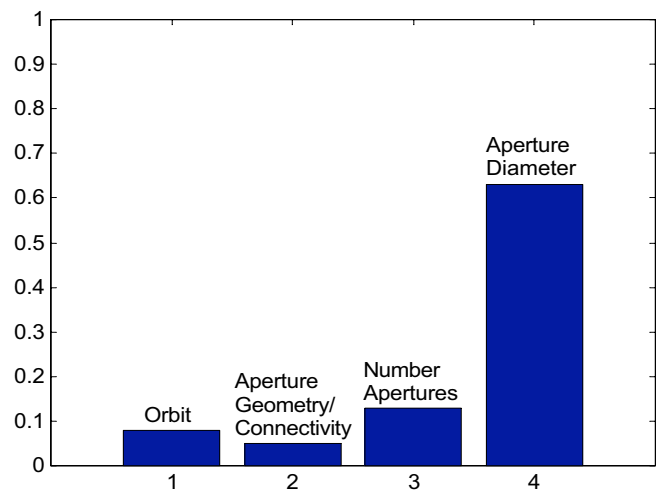


Step 5 – Interpret Results: Sensitivity Analysis



- **Finite Differencing**
 - Computationally expensive
 - Local Sensitivity
- **Key Question:** Which **variables** in the design vector have the most significant **effect** on the **metrics** of interest for **system**?
- **Analysis of Variance (ANOVA)**
 - A **statistical technique** used to detect differences in the average performance of groups of items tested.
- **ANOVA** provides the systems engineer with a tool to identify key models and guide **technology investment strategies** during the **Conceptual Design Phase** of a program.

e



$$SS_T = \sum_{i=1}^N (y_i - \bar{T})^2$$

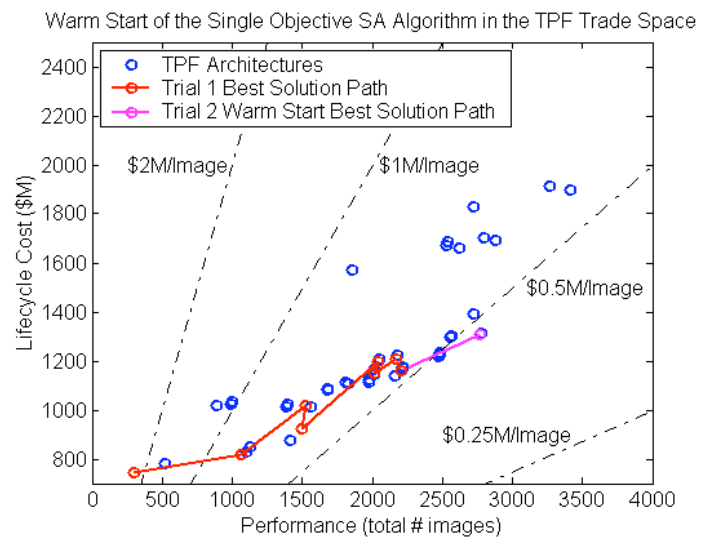
$$SS_\gamma = \sum_{i=1}^n n_{\gamma_i} (\bar{y}_{\gamma_i} - \bar{T})^2$$

$$RI = \left[\frac{SS_\gamma}{SS_T} \right] \times 100$$

Step 6 – Iterate



- Model Fidelity
- Simulated Annealing Algorithm Parameters
 - Cooling Schedule
 - DOF
- “Warm Starting”
- Run additional trials



Warm Start Example

State	Orbit (AU)	Number Apertures	Collector Connectivity/Geometry	Aperture Diameter (m)	Cost Per Image (\$K)
Trial 1 Initial Architecture	1	4	SCI-1D	1	2475
Trial 1 Final Architecture	4.5	8	SCI-2D	3	526
Trial 2 Warm Start Initial Architecture	4.5	8	SCI-2D	3	526
Trial 2 Warm Start Final Architecture	4.5	8	SCI-2D	4	471

Step 7 – Recommended Architectures



- **Single Objective DSS Conceptual Design Problem**
 - The best **family(s)** of architectures with respect to the metric of interest found by the single objective simulated annealing algorithm.
- **Multiobjective DSS Conceptual Design Problem**
 - The **Pareto optimal set** with respect to the selected decision criteria as found by the multiobjective, multiple solution simulated annealing algorithm.
 - Budget Capping, Multiattribute Utility Theory, Uncertainty Analysis, Flexibility, and Policy Implications

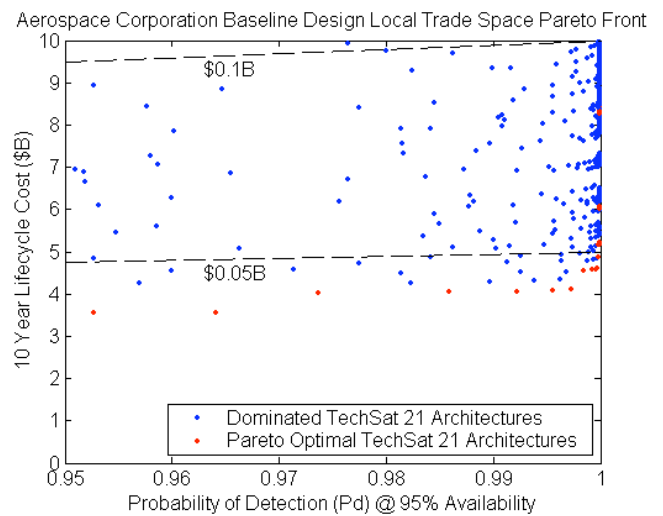
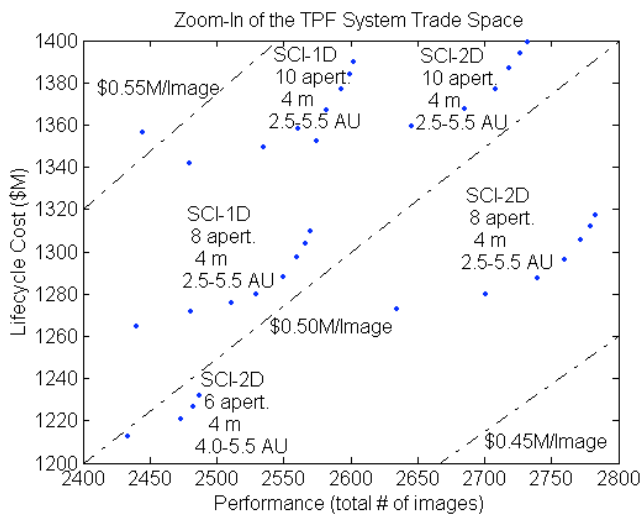
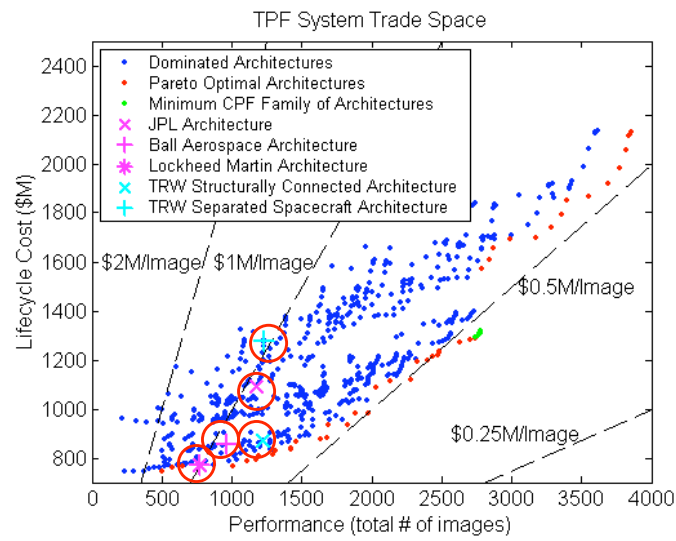


Chart: 18

Terrestrial Planet Finder Case Study – Results (1)



Architecture	MMDOSA Minimum CPF (% Improvement)	Pareto Optimal Equivalent Performance (% Improvement)	Pareto Optimal Equivalent LCC (% Improvement)
JPL	49%	28%	73%
Ball Aerospace	47%	10%	52%
Lockheed Martin	53%	0%	31%
TRW SCI	34%	7%	20%
TRW SSI	55%	37%	119%

Chart: 19

Terrestrial Planet Finder Case Study – Results (2)

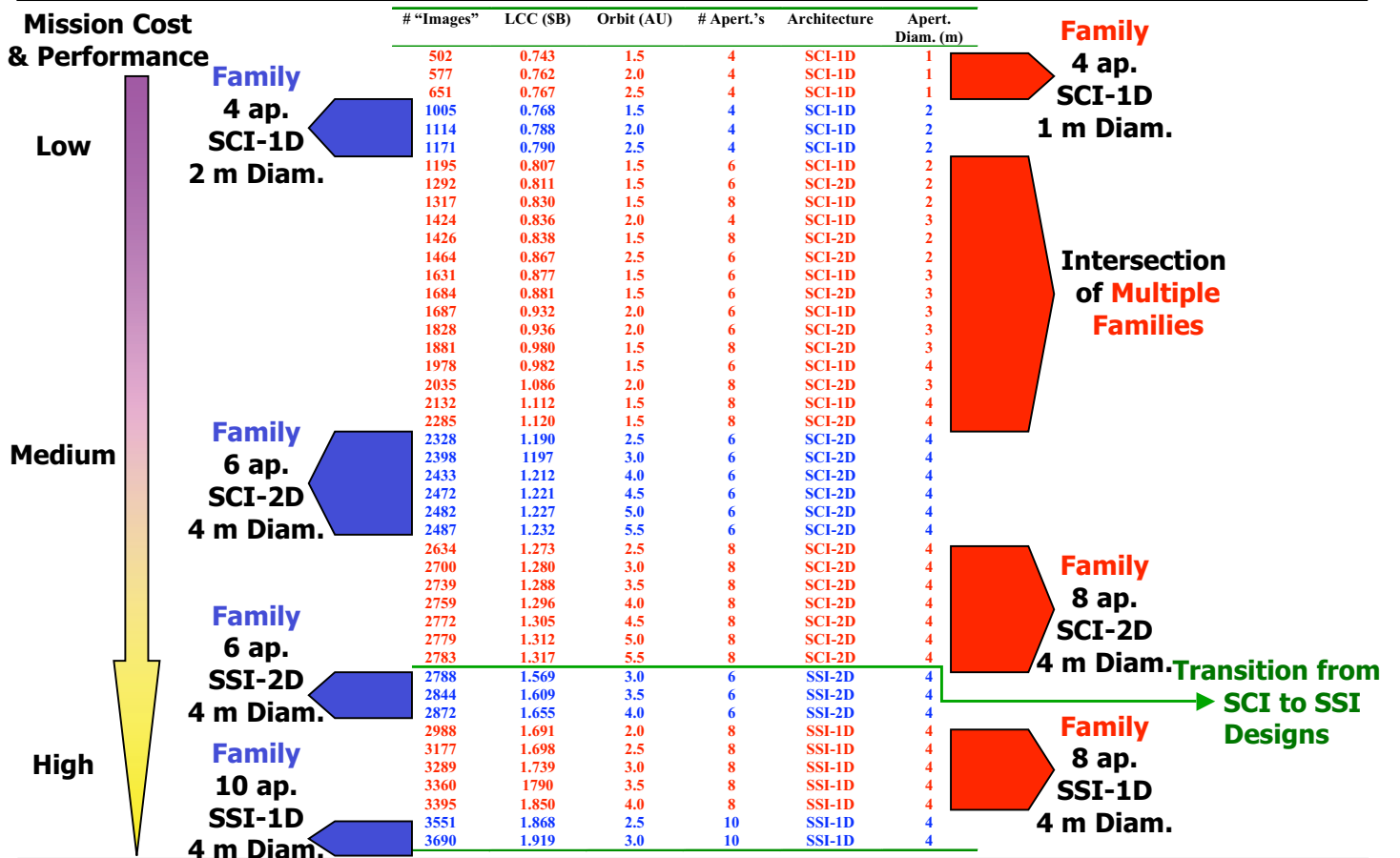
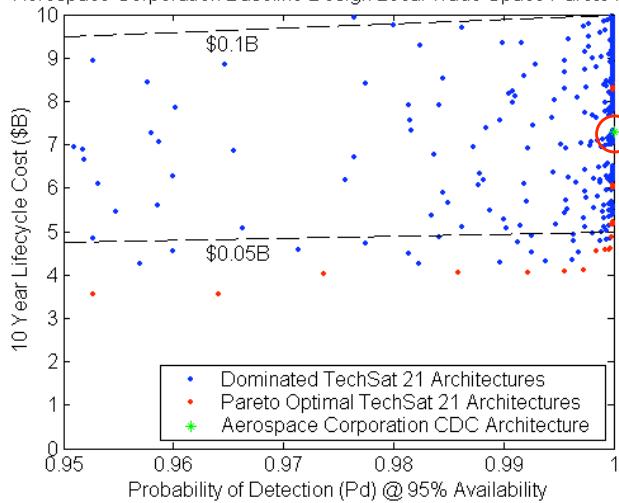


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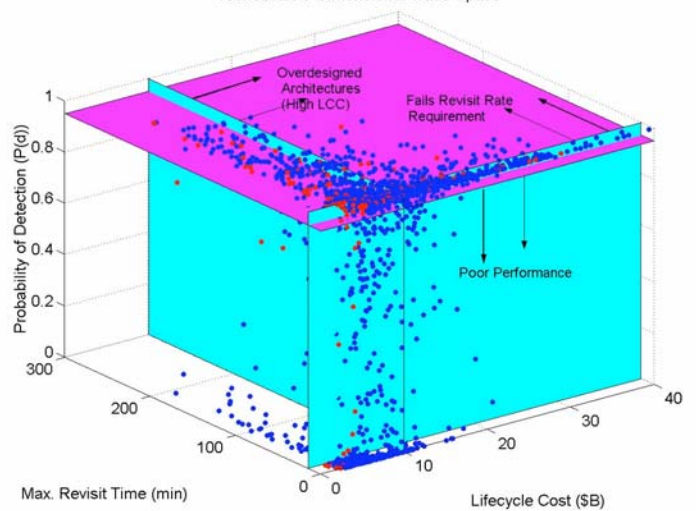
TechSat 21 Case Study – Results



Aerospace Corporation Baseline Design Local Trade Space Pareto Front



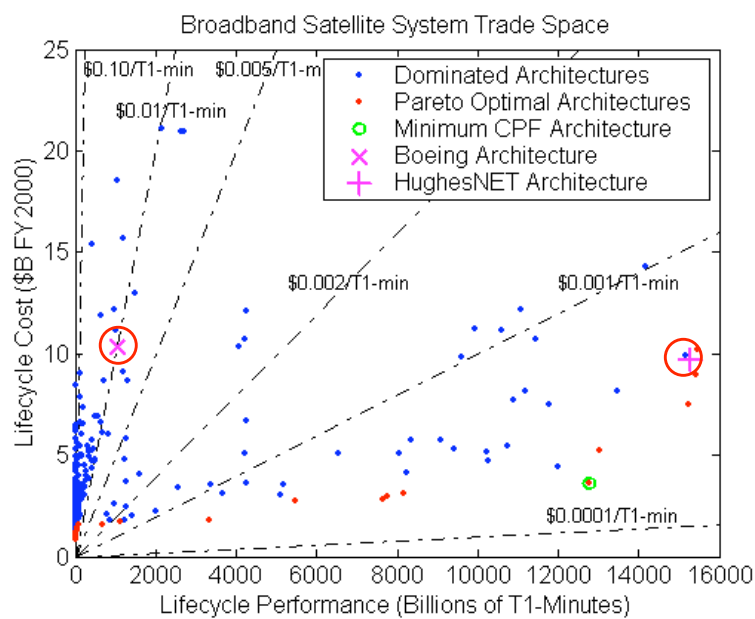
TechSat 21 3-Dimensional Trade Space



Architecture	CPF % Improvement	Lifecycle Cost % Improvement	Probability of Detection % Improvement	Max. Revisit Time % Improvement
CDC Trade Space	49%	51%	-4%	0%
Global Trade Space - SO	65%	66%	-3%	13%
Global Trade Space - MO	54%	57%	-5%	67%

Chart: 21

Broadband Communication Case Study – Results (1)



Architecture	MMDOSA Minimum CPF (% Improvement)	Pareto Optimal Equivalent Performance (% Improvement)	Pareto Optimal Equivalent LCC (% Improvement)
Boeing	97%	85%	1392%
HughesNet	59%	22%	1%

Chart: 22

Broadband Communication Case Study – Results (1)



Mission Cost & Performance

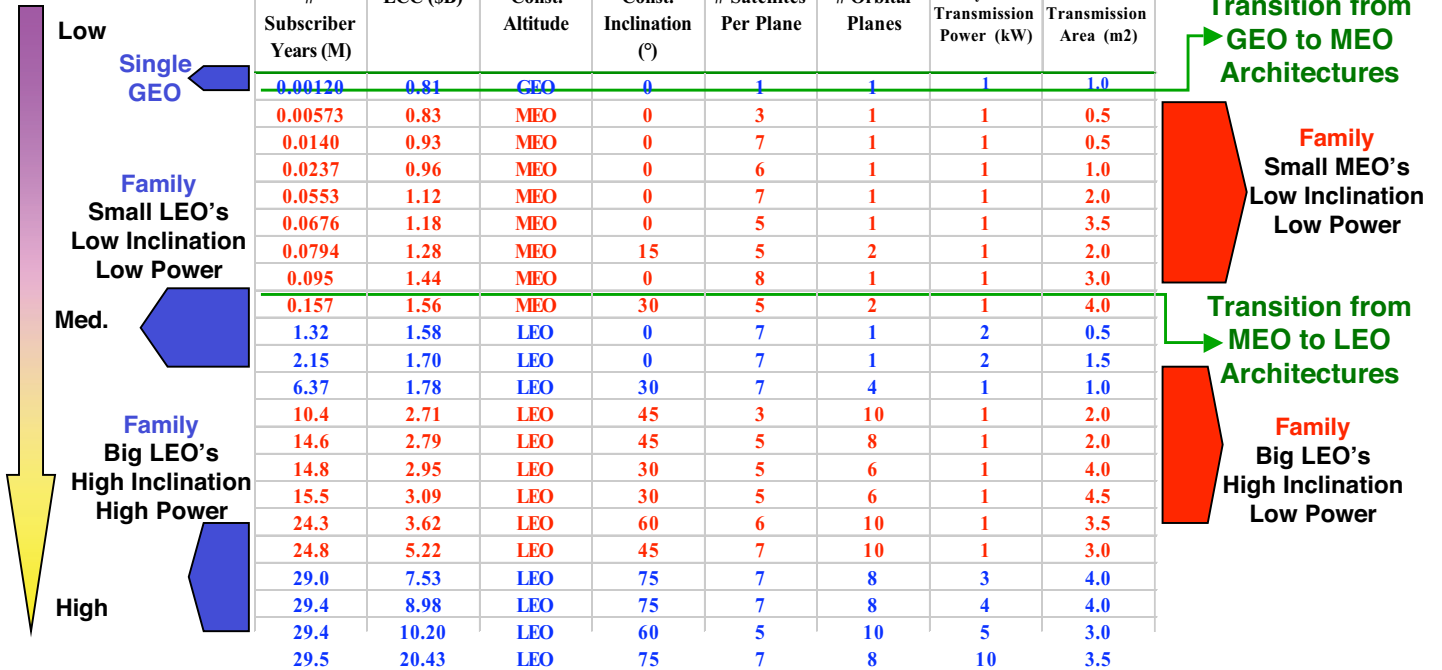


Chart: 23

Thesis Contributions (1)



- Developed a **methodology** for mathematically formulating **DSS** conceptual design problems as **nonlinear multiobjective optimization** problems.
- Determined that a heuristic **simulated annealing** technique finds the best system architectures with **greater consistency** than Taguchi, gradient, and univariate techniques when searching a nonconvex DSS trade space.
- Created **two new multiobjective variants** of the core simulated annealing (SA) algorithm – the multiobjective single solution SA algorithm and the multiobjective multiple solution SA algorithm.
- For each of the **three case study missions**, identified specific architectures that provide **higher levels of performance** for **lower lifecycle costs** than prior proposed designs.

Thesis Contributions (2)



- Created a method for computing the **simulated annealing Δ -parameter**, originally developed and intended for single objective optimization problems, for **multiobjective** optimization problems.
- Gathered empirical evidence that the **2-DOF** variant of the simulated annealing algorithm is the **most effective** at both single objective and multiobjective searches of a DSS trade space.
- Developed an **integer programming** approach to model and solve the DSS **launch vehicle selection** problem as an optimization problem.