

3/3/03  
10.537

# MACROSCOPIC MATERIAL PROPERTIES

- MOTIVATION
- STRESS & STRAIN
- RELATE STRESS & STRAIN  $\Rightarrow$  HOOKE'S LAW
- MEASURABLES

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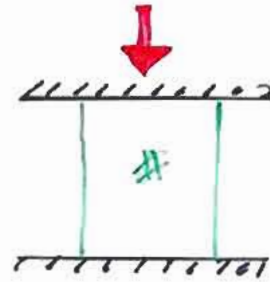
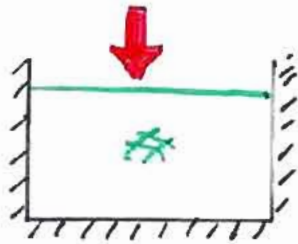
Figure 3, graph of "Tensile stress-strain behavior of N. Clavipes spider silk compared to other textile fibers." In Ko, Frank K., et al. "Engineering Properties of Spider Silk." *MRS Symposium Proceedings*, Vol. 702 (Fall 2001 meetings), paper U1.4.

Image removed due to copyright considerations.

"Swelling of Connective Tissues: Confined Compression," shown through graph of stress vs. strain for Bovine Articular Cartilage.

# MACROSCOPIC TISSUE-LEVEL BIOMECHANICS

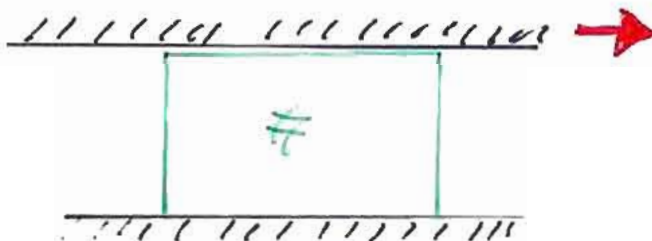
- COMPRESSION



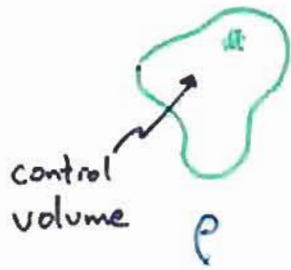
- TENSION



- SHEAR



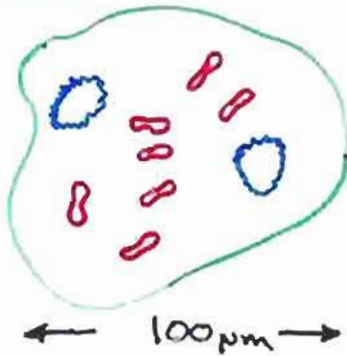
# CONTINUUM MECHANICS?



shrink  
→



consider blood...

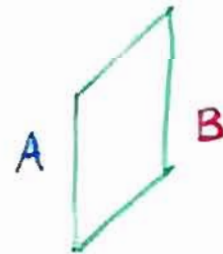
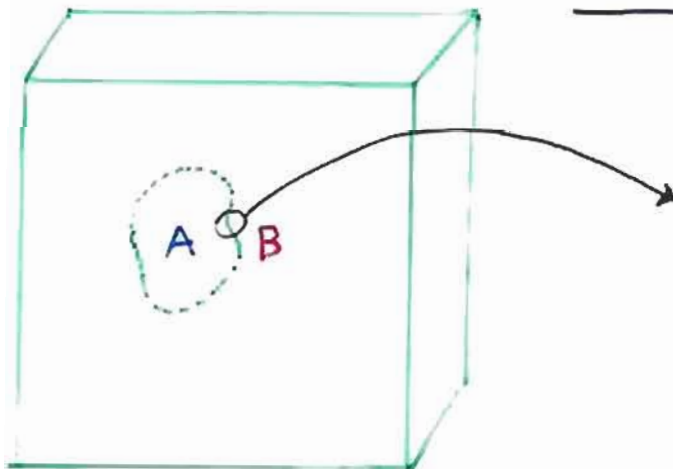


shrink?  
→

bounds set by  
physical length scales...  
CELLS, MOLECULES ETC..

## THE CONCEPT OF STRESS

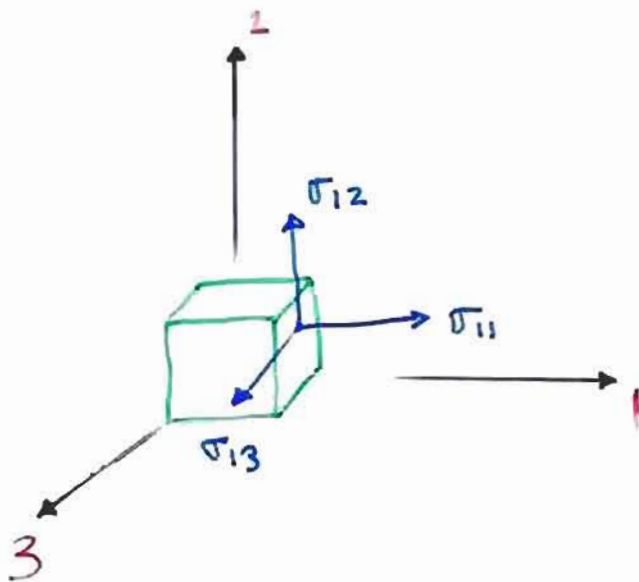
SURFACE FORCES (NOT BODY)



DIMENSIONS : FORCE/AREA

UNITS :  $N/m^2$ , Pa

# STRESS NOTATION



$\sigma_{ij}$  STRESS TENSOR

$i$ -component of the force exerted on a plane described by the outward normal in the  $j$ -direction.

STRESS VECTOR

$$T_i = \sigma_{ij} n_j$$



FORCE/AREA ON A SURFACE DESCRIBED BY THE NORMAL  $n_i$

$$\sigma_{ij} = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix}$$

SHEAR COMPONENTS

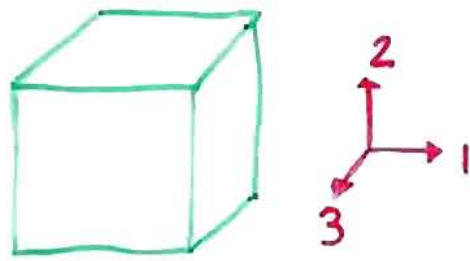
NORMAL COMPONENTS

9 UNKNOWNS

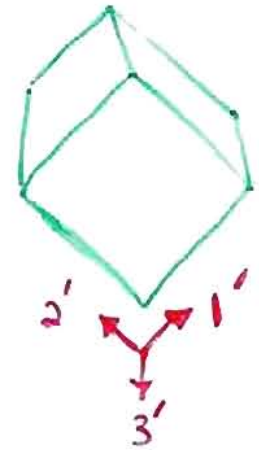
No BODY TORQUES  $\Rightarrow \sigma_{ij} = \sigma_{ji}$  symmetric

USING SYMMETRY  $\Rightarrow$  6 UNKNOWNS

# PRINCIPAL STRESS COMPONENTS



ROTATION OF  
COORD. SYSTEM



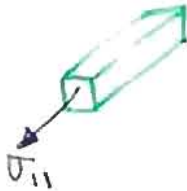
$$\sigma_{ij} = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix}$$

lost info?  
no.

$$\sigma'_{ij} = \begin{bmatrix} \sigma'_{11} & 0 & 0 \\ 0 & \sigma'_{22} & 0 \\ 0 & 0 & \sigma'_{33} \end{bmatrix}$$

SHEAR STRESSES = 0

## SIMPLE CASES



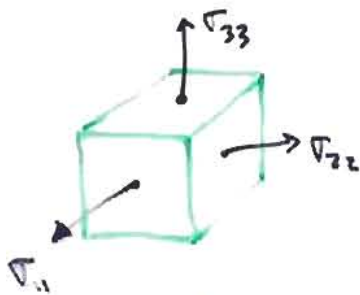
UNIAXIAL  
TENSION

$$\begin{bmatrix} \sigma_{11} & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$



BIAXIAL  
TENSION

$$\begin{bmatrix} \sigma_{11} & 0 & 0 \\ 0 & \sigma_{22} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$



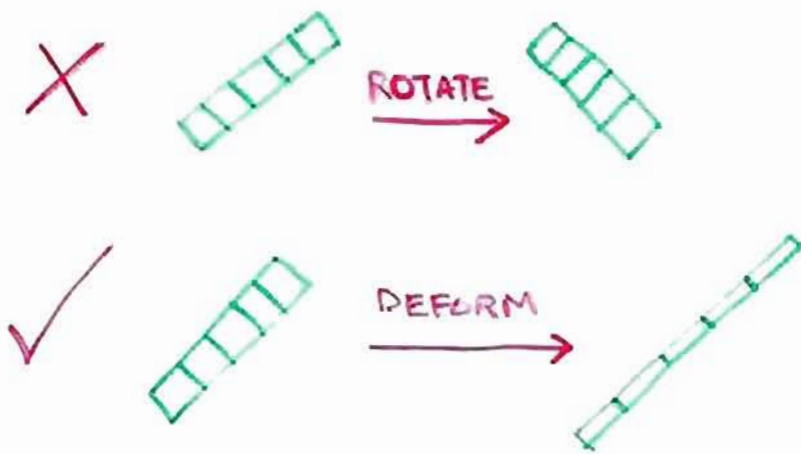
TRIAxIAL  
TENSION

$$\begin{bmatrix} \sigma_{11} & 0 & 0 \\ 0 & \sigma_{22} & 0 \\ 0 & 0 & \sigma_{33} \end{bmatrix}$$

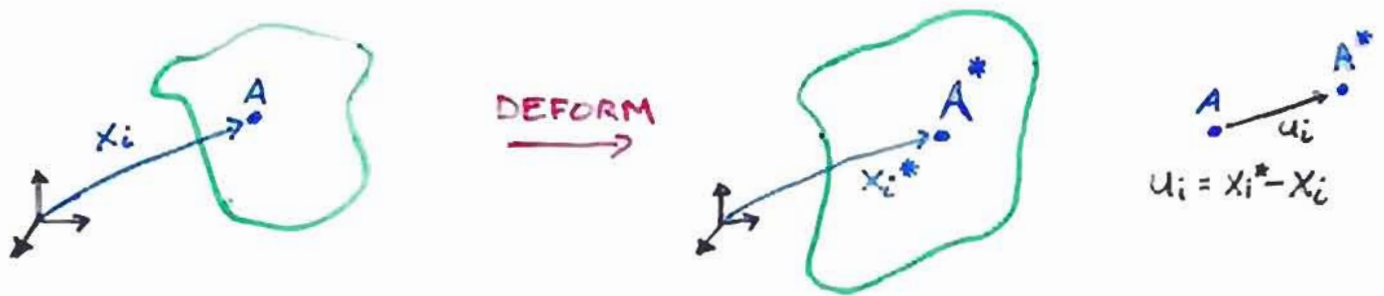
(PRESSURE)

# STRAIN

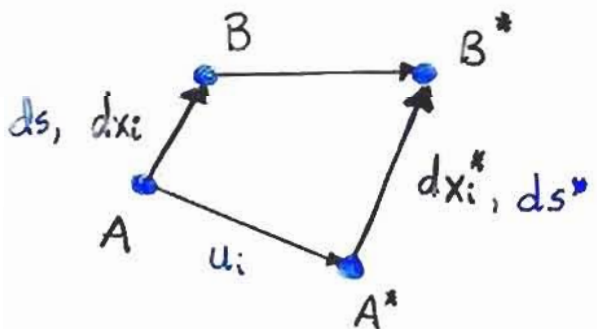
⚠ STRAIN describes deformation (not rigid body rotation or translation) in terms of relative displacements.



MORE GENERALLY:



NEED 2 POINTS OR CANNOT DISTINGUISH DISPLACEMENT FROM DEFORMATION



'd' denotes a small quantity.

MEASURE OF 'DEFORMATION':  $ds^{*2} - ds^2$

$$dx_i^* dx_i^* - dx_i dx_i$$



# STRAIN CONT.

$$x_i^* = x_i + u_i$$

$$dx_i^* = \frac{\partial x_i^*}{\partial x_j} dx_j = \frac{\partial u_i}{\partial x_j} dx_j + \underbrace{dx_j \delta_{ij}}_{dx_i}$$

Now USE IN:

$$dx_i^* dx_i^* - dx_i dx_i = \left( \frac{\partial u_i}{\partial x_j} + \delta_{ij} \right) \left( \frac{\partial u_i}{\partial x_k} + \delta_{ik} \right) dx_j dx_k - dx_i dx_i$$

EXPAND ...

$$= \left( \frac{\partial u_i}{\partial x_k} \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_k} + \frac{\partial u_k}{\partial x_j} + \delta_{jk} \right) dx_j dx_k - dx_i dx_i$$

$$= \left( \underbrace{\frac{\partial u_i}{\partial x_k} \frac{\partial u_i}{\partial x_j}}_{\epsilon^2} + \underbrace{\frac{\partial u_j}{\partial x_k}}_{\epsilon} + \underbrace{\frac{\partial u_k}{\partial x_j}}_{\epsilon} \right) dx_j dx_k$$

ASSUME SMALL DEFORMATION...

OK SINCE AFTER A LINEAR THEORY

$$dx_i^* dx_i^* - dx_i dx_i = \left( \frac{\partial u_j}{\partial x_k} + \frac{\partial u_k}{\partial x_j} \right) dx_j dx_k$$

$$dx_i^* dx_i^* - dx_i dx_i = 2 \underbrace{\epsilon_{jke}}_{\text{STRAIN TENSOR}} dx_j dx_k$$

$$\epsilon_{jke} \equiv \frac{1}{2} \left( \frac{\partial u_j}{\partial x_k} + \frac{\partial u_k}{\partial x_j} \right)$$



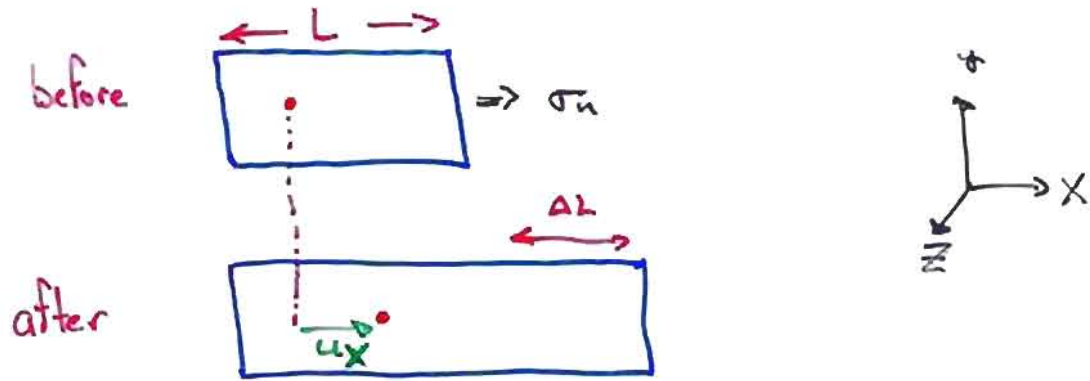
• SYMMETRIC  $\epsilon_{ij} = \epsilon_{ji}$

•  $\epsilon_{jke} = 0$  FOR SOLID BODY ROTATION



# PHYSICAL INTERPRETATION OF STRAIN

Homogeneous Elongation

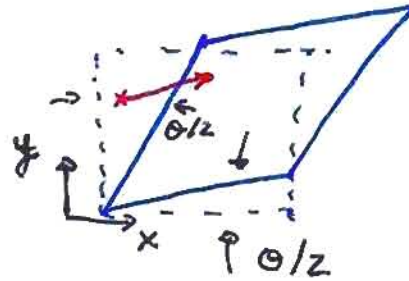
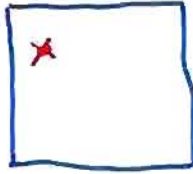


$$u_x = \frac{\Delta L}{L} x$$

$$\epsilon_{xx} = \frac{\partial u_x}{\partial x} = \frac{\Delta L}{L}$$

# Strain: SHEAR DEFORMATIONS

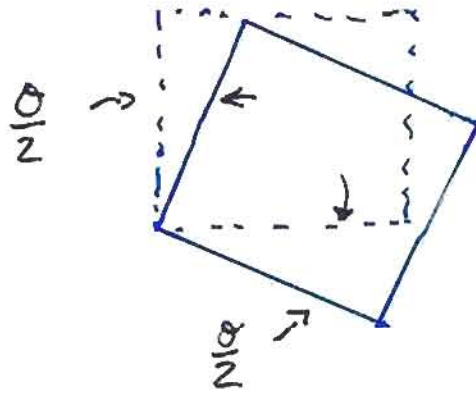
before



$$\left. \begin{aligned} u_x &\approx \frac{\theta}{2} y \\ u_y &\approx \frac{\theta}{2} x \end{aligned} \right\} \rightarrow \epsilon_{xy} = \epsilon_{yx} = \frac{1}{2} \left( \frac{du_x}{dy} + \frac{du_y}{dx} \right)$$

$$\epsilon_{xy} = \frac{1}{2} \left( \frac{\theta}{2} + \frac{\theta}{2} \right) = \frac{\theta}{2}$$

CONSIDER SOLID BODY ROTATION:



$$\left. \begin{aligned} u_x &\approx \frac{\theta}{2} y \\ u_y &\approx -\frac{\theta}{2} x \end{aligned} \right\} \rightarrow \epsilon_{xy} = 0!$$

## RECALL FLUID DYNAMICS

$$\rho \frac{Dv_i}{Dt} = \rho g_i + \frac{\partial}{\partial x_j} \sigma_{ij}$$

$$\sigma_{ij} = -p \delta_{ij} + \tau_{ij}$$

CONSTITUTIVE RELATION FOR  $\tau_{ij}$

postulate

$$\tau_{ij} = C_{ijae} \underbrace{\frac{\partial v_a}{\partial x_e}}_{\text{velocity gradients}}$$

⋮

$$\tau_{ij} = 2\mu E_{ij}$$

NEWTONIAN  
INCOMPRESSIBLE  
FLUID

RATE OF STRAIN TENSOR

$$E_{ij} = \frac{1}{2} \left[ \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right]$$

FOR NEWTONIAN FLUIDS THE STRESS DEPENDS ON STRAIN-RATE.

DIMENSIONS:

$$ML^{-1}T^{-2} = [\mu] T^{-1}$$

$$[\mu] = ML^{-1}T^{-1}$$

$$[G] = ML^{-1}T^{-2}$$

# GENERALIZED HOOKE'S LAW

• CONSTITUTIVE RELATION

• LINEAR ELASTICITY

$$\text{STRESS} \rightarrow \sigma_{ij} = \underbrace{C_{ijkl}}_{\substack{\text{MODULI} \\ \text{(MATERIAL PROPERTIES)}}} \epsilon_{kl}$$

↓ COMPLIANCE'

$$\rightarrow 3^4 = 81$$

lots of experiments!

SIMPLIFY : IDEAL & ISOTROPIC MATERIAL

• symmetry of  $\sigma_{ij} \Rightarrow C_{ijkl} = C_{jilk}$

• symmetry of  $\epsilon_{kl} \Rightarrow C_{ijlk} = C_{ijkl}$

• assume isotropic material  $\Rightarrow$  invariant to coord. trans.

↓  
 $C_{ijkl}$  4<sup>th</sup> order isotropic tensor

GENERAL FORM:

$$C_{ijkl} = \lambda \delta_{ij} \delta_{kl} + G (\delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk})$$

REDUCED TO 2 MODULI (EXPERIMENTS)

$\lambda$  &  $G \rightarrow$  Lamé elastic constants (1852)

— DILATION

$$\sigma_{ij} = \lambda \delta_{ij} \epsilon_{kk} + 2G \epsilon_{ij}$$

2<sup>nd</sup> Lamé constant

— SHEAR MODULUS

$$G = \frac{E}{2(1+\nu)} \quad ; \quad \lambda = \frac{\nu E}{(1+\nu)(1-2\nu)}$$

$\nu$  = POISSON'S RATIO

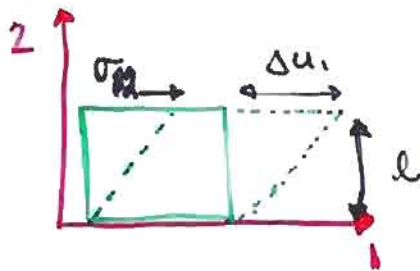
$E$  = YOUNG'S MODULUS

⋮

$$\epsilon_{ij} = \frac{1+\nu}{E} \sigma_{ij} - \frac{\nu}{E} \sigma_{kk} \delta_{ij}$$

PHYSICAL MEANINGS ...

① SHEAR



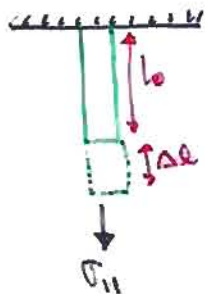
$$\sigma_{12} = 2G \epsilon_{12}$$

$$\epsilon_{12} = \frac{1}{2} \left( \frac{\partial u_1}{\partial x_2} + \frac{\partial u_2}{\partial x_1} \right)$$

MEASURE

$$\sigma_{12} = G \frac{\Delta u_1}{l} = G \frac{\partial u_1}{\partial x_2}$$

② EXTENSION



$\sigma_{22} = \sigma_{33} = 0$  FREE SURFACE

$$\sigma_{11} / \epsilon_{11} = E$$

consider  $\epsilon_{22}$

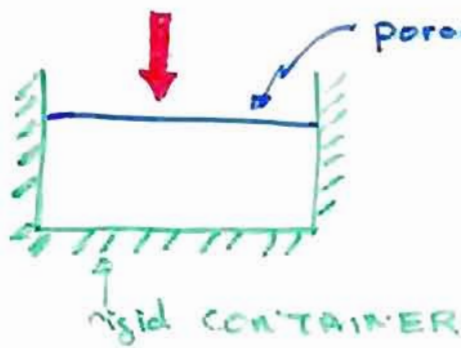
$$\epsilon_{22} = \frac{1+\nu}{E} \sigma_{22} - \frac{\nu}{E} (\sigma_{11} + \sigma_{22} + \sigma_{33})$$

thus  $\epsilon_{22} = -\frac{\nu}{E} \sigma_{11}$  ; likewise  $\epsilon_{33} = -\frac{\nu}{E} \sigma_{11}$

$$\nu = -\frac{\epsilon_{22}}{\epsilon_{11}}$$

③

CONFINED COMPRESSION



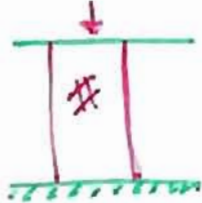
$$\epsilon_{22} = \epsilon_{33}$$

$$\sigma_{11} = \underbrace{(2G + \lambda)}_H \epsilon_{11}$$

compressive modulus

④

UNCONFINED COMPRESSION



$$\sigma_{22} = \sigma_{33} = 0$$

$$E = \frac{\sigma_{11}}{\epsilon_{11}}$$

⑤

HYDROSTATIC PRESSURE



$$\sigma_{11} = 2G \epsilon_{11} + \lambda \epsilon_{kk}$$

$$\sigma_{22} = 2G \epsilon_{22} + \lambda \epsilon_{kk}$$

$$\sigma_{33} = 2G \epsilon_{33} + \lambda \epsilon_{kk}$$

$$\frac{\sigma_{kk}}{3} = \underbrace{\left(1 + \frac{2}{3}G\right)}_K \epsilon_{kk}$$

BULK MODULUS

↪ Dilation

↖ negative of pressure

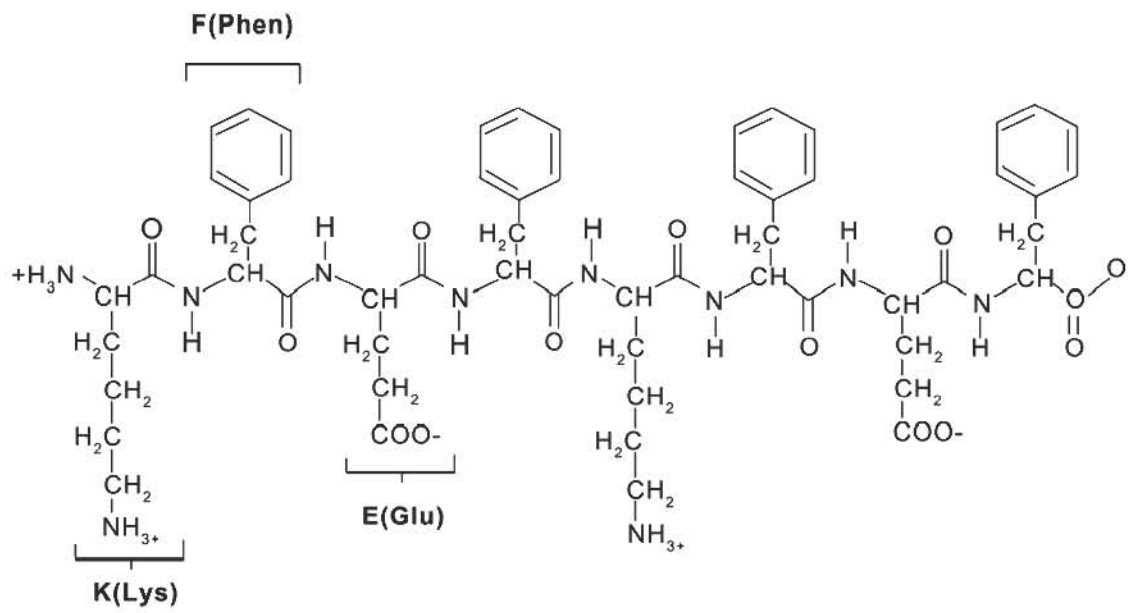
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"Self Assembling Peptides." Source: Marini, Kamm, et al., 2002.  
Four photographs at 8 min, 35 min, 2 hrs, 30 hrs.

Image removed due to copyright considerations.

"Self Assembling Peptide Gel." Source: S. Zhang et al.,  
Figure 5 (Scanning electron micrographs).

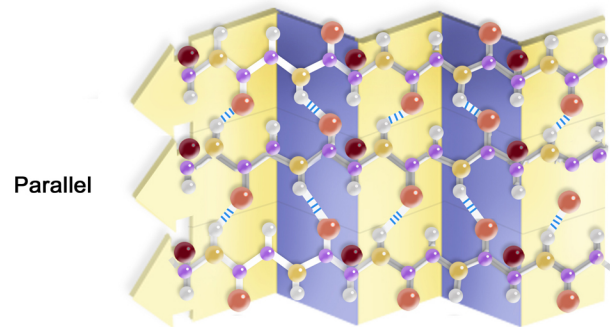
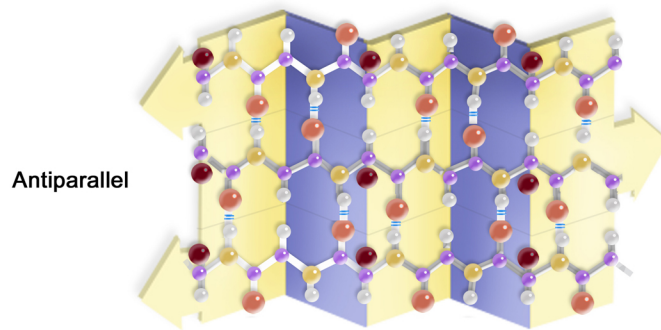
### Molecular structure of the oligopeptide, EFK8





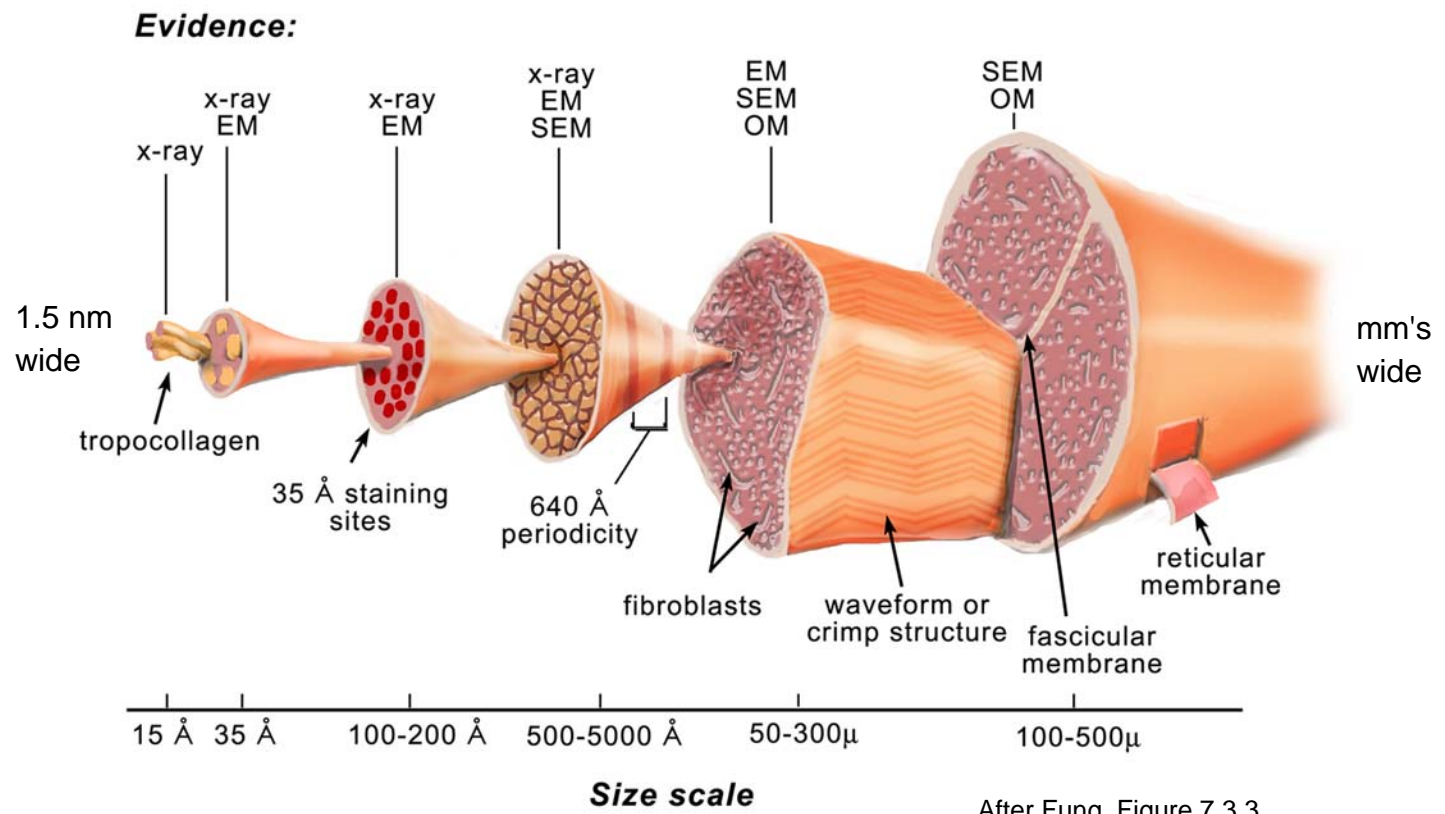
# Protein Structure and Function

## $\beta$ -sheets



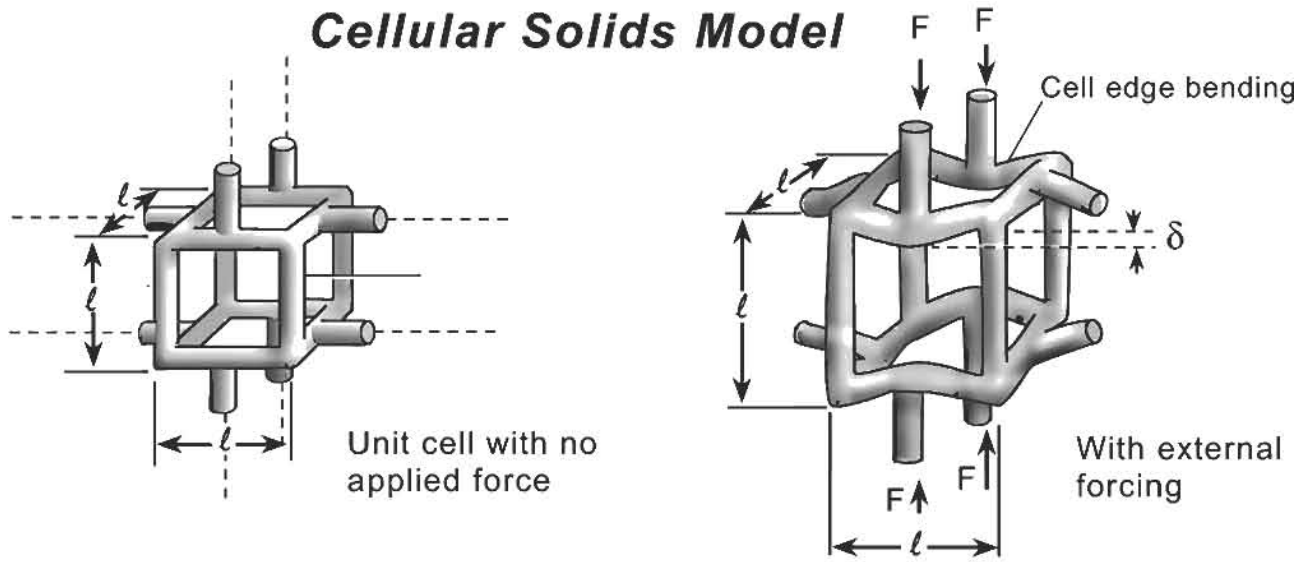
COLLAGEN! Complex Structure Affects Equil. Mecham.  
Properties Independ. of  
Fluid Flow

### Tendon Hierarchy

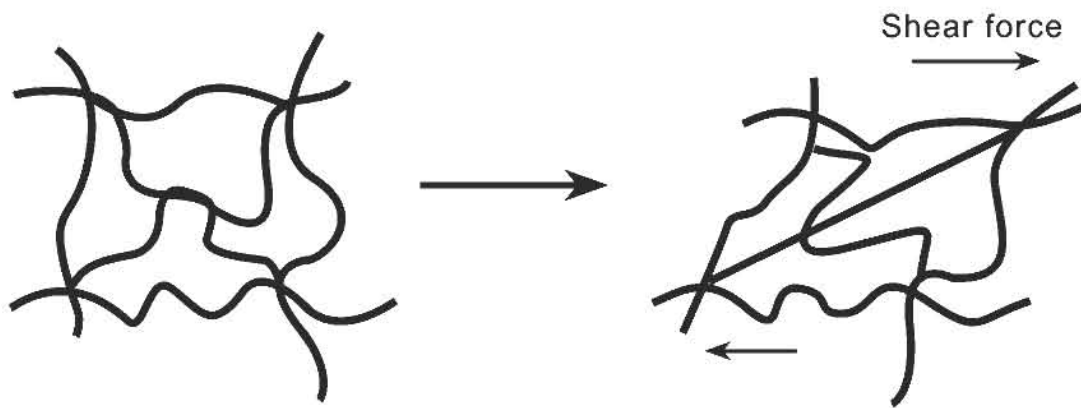


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Figure 7.3.4 and 7.3.5 in Fung, Y. C. *Biomechanics: Mechanical Properties of Living Tissues*.  
New York: Springer-Verlag, 1993.

### Cellular Solids Model



### Biopolymer Model



## SUMMARY

- STRESS & STRAIN
- HOOKE'S LAW  $\sigma \sim \epsilon$ 
  - ideal, isotropic material  $\Rightarrow$  2 material properties
  - $\sigma_{ij} = \lambda \delta_{ij} \epsilon_{kk} + 2G \epsilon_{ij}$
  - $\epsilon_{ij} = \frac{1+\nu}{E} \sigma_{ij} - \frac{\nu}{E} \sigma_{kk} \delta_{ij}$
- MEASUREMENTS
  - $E, G, \nu, H, K$
- SELF ASSEMBLED PEPTIDES