10.675 LECTURE 4

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1. Today

- \rightarrow Dirac Notation
- \rightarrow Exploring PES
- \rightarrow Algorhythms for Geometry Optimization
- \rightarrow Zero Point Energies and Stat Mech.

2. Concepts

minima and transition states.

3. PES - POTENTIAL ENERGY SURFACE

Example: Rotation of carbon-carbon bond in ethane (C_2H_6) .



In general, one can look at E_o as a function of any parameter. In this example, we will use orientation. 3N - 6 degrees of freedom.

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BO approximation (atoms are fixed, nuclei mass is infinite).



4. Method

$$\begin{split} H_i^{method} \Psi_i &= \epsilon_i \Psi_i \\ H_i^{method} &= \frac{-1}{2} \nabla^2 - \sum^N \frac{Z_k}{r_{1K}} + V_1^{method} \\ \text{Where } V_1 \text{ varies depending on the method we are using.} \\ \text{Examples of Methods: Molecular obital vs Density functional theory.} \\ V_i^{method} &= \sum_{j=2}^N \int \frac{\rho(r_j)}{\vec{r_i} - \vec{r_j}} d\vec{r_j} + V_i^{\chi method} + V_i^{Cmethod} \\ \text{Where } \sum_{j=2}^N \int \frac{\rho(r_j)}{\vec{r_i} - \vec{r_j}} d\vec{r_j} \text{ is the mean field term.} \\ V_i^{\chi method} \text{ exchange term (pauli exchange)} \\ V_i^{Cmethod} \text{ correlation term.} \\ \text{Use a trial basis set } \Psi_i &= \sum_i c_{ij} g_j \\ \text{SOLVE } E_o &= \sum_1^N \int \Psi_i^* H_i^{method} \Phi_i d\vec{r} + \text{ Nuc - Nuc terms.} \end{split}$$

5. Solving

Need to find c_{ij} 's which minimize E_o . Here's the detailed method.

- 1) Choose molecule nuclear positions + num of electrons
- 2) Choose method
- 3) Choose basis set
- 4) Choose initial guess for $c'_{ij}s$
- 5) Solve Eigenvalue equation for new $c_i j$'s
- 6) Is $E_{old} E_{new} < ATOL?$
- 7) If no, return to step 4 with new c_{ij} 's
- 7b) If yes, calculate the forces on the nuclei
- 8) Is the $force < force^{ATOL}$? If yes, finished.
- 9) If not, update geometry, goto step 4.

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6. Details

$$\begin{split} E_o^{elec} &= V^{nucleous} = E(\vec{x}) \text{ meaning the energy of the electron is dependent on the potential of the nuclei.} \\ \vec{x} &= 3N = (R_{1x}, R_{1y}, R_{1z}, R_{2x}, R_{2y}, \ldots) \\ \text{In the geometry optimization, we want to minimize such that} \\ dE/dx &= 0or < ATOL. \\ \text{expand } E_{k+1}(\vec{x}_{k+1}) = E_k + \vec{g}_k^t \cdot (\vec{x}_{k+1} - \vec{x}_k) + 1/2(\vec{x}_{k+1} - \vec{x}_k)^T \bar{\beta}_k(\vec{x}_{k+1} - \vec{x}_k) \\ \text{Where: k is the step} \\ \vec{g}_k^t \text{ are the gradient forces} \\ \bar{\beta}_k \text{ is the Hessian Matrix.} \\ \text{SCF gives us } E_o, \vec{g}. \text{ Then, update } \bar{\beta}_k \text{ and it's inverse } \bar{H}_k \\ \frac{dE_{k+1}}{dx_{k+1}} &= \vec{g}_{k+1}g_k + \bar{\beta}_k(\vec{x}_{k+1} - x_k) = 0 \\ \to \vec{P} \text{ step size to move atoms to next position.} \\ \vec{P}_k &= \vec{x}_{k+1} - vecx_k = \bar{\beta}_k^{-1}\vec{g}_k = -\bar{H}_k\vec{g}_k \end{split}$$

7. UPDATING $\bar{\beta}_k$

Method \rightarrow steepest descent.