Course 12.520, Geodynamics Prof. Brad Hager Lecture 26: Corner Flow

Why aren't subducted slabs curled over or vertical?

What is the flow pattern beneath oceanic ridges?

Does constant thickness basaltic crust make sense?



Figure 26.1

Corner flow models:

Batchelor – Introduction to fluid mechanics McKenzie – GJRAS <u>18</u>, 1-32, 1969 Stevenson & Turner, Nature, <u>270</u>, 334-336, 1977 Tovish et al, JGR <u>83</u>, 5892, 1978 McAdoo, JGR, <u>87</u>, 8684, 1982

Slab model:



Stokes equation

$$0 = \eta \nabla^2 v + \rho \nabla U - \nabla p$$
$$0 = \nabla \cdot v$$

Use vorticity

$$\omega = \nabla \times v$$

Take curl of Stokes equation (heading toward 4th order equation) $0 = \eta \nabla \times \nabla^2 v + \nabla \times (\rho \nabla U - \nabla p)$

Recall $\nabla \times (\nabla \varphi) = 0, \nabla \cdot (\nabla \times \underline{A}) = 0$

Assume ρ constant

Recall $\nabla^2 \underline{v} = \nabla (\nabla \cdot \underline{v}) - \nabla \times \nabla \times v$

Figure by MIT OCW.

$$0 = -\eta \left(\nabla \times \nabla \times \nabla \times \nu \right)$$
$$= -\eta \left(\nabla \times \nabla \times \omega \right)$$
$$= \eta \nabla^2 \omega$$

Next – define stream function ψ by $v = \nabla \times \psi$ Automatically satisfies $\nabla \cdot v = 0$ Then $\psi = \nabla \times \nabla \times \psi = -\nabla^2 \psi$

For our purposes, consider 2-D flow only

 $\psi = (0, 0, \psi)$ r, θ , z Must solve scalar equation $\nabla^2 (\nabla^2 \psi) = 0$ $\nabla^4 \psi = 0 \quad \leftarrow \text{Biharmonic equation [Recall Airy stress function]}$

To help in guessing solution, recall

$$\begin{split} v_r &= \frac{1}{r} \frac{\partial \psi}{\partial \theta} \\ v_\theta &= -\frac{\partial \psi}{\partial r} \\ \tau_{rr} &= -p + 2\eta \frac{\partial v_r}{\partial r} \\ \tau_{\theta\theta} &= -p + 2\eta \left(\frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r} \right) \\ \tau_{r\theta} &= \eta \left(\frac{1}{r} \frac{\partial v_r}{\partial \theta} + \frac{\partial v_\theta}{\partial r} - \frac{v_\theta}{r} \right) \\ \nabla^2 \psi &= \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \psi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \psi}{\partial \theta^2} + \frac{\partial^2 \psi}{\partial z^2} \end{split}$$

Let's try solutions

$$\psi = R(r)\Theta(\theta)$$

We will want solutions with v_r independent of r

Try
$$R(r) = r$$

 $\psi = r\Theta$
Plugging in $\Rightarrow \frac{d^4\Theta}{d\theta^4} + 2\frac{d^2\Theta}{d\theta^2} + \Theta = 0$,
or Θ ""+ 2 Θ "+ $\Theta = 0$
Solution:

 $\Theta = A\sin\theta + B\cos\theta + C\theta\sin\theta + D\theta\cos\theta$

Now – match boundary conditions

$$v_r = \Theta' = A\cos\theta - B\sin\theta + C(\sin\theta + \theta\cos\theta) + D(\cos\theta - \theta\sin\theta)$$
$$v_{\theta} = -\Theta$$

Slab problem -

Break into 2 regions

Back-arc region		Fore-arc region	
$\theta = 0$	$v_{\theta} = 0 = B$	$\theta = 0$	$v_{\theta} = 0$
	$v_r = 0 = A + D$		$v_r = -v$
$\theta = \theta_{B}$	$v_{\theta} = 0 = A\sin\theta_{B} + C\theta_{B}\sin\theta_{B} + D\theta_{B}\cos\theta_{B}$	$\theta = \theta_F$	$v_{\theta} = 0$
	$v_r = v$		$v_r = v$
	$= A\cos\theta_{B} + C\left(\sin\theta_{B} + \theta_{B}\cos\theta_{B}\right) + D\left(\cos\theta_{B} - \theta_{B}\sin\theta_{B}\right)$		

Need to solve 3 equations, 3 unknowns

Solutions

Back-arc

$$\psi = \frac{rv\left[\left(\theta_b - \theta\right)\sin\theta_b\sin\theta - \theta_b\theta\sin\left(\theta_b - \theta\right)\right]}{\theta_b^2 - \sin^2\theta_b}$$

Fore-arc

$$\psi = \frac{-rv\left[\left(\theta_f - \theta\right)\sin\theta + \theta\sin\left(\theta_f - \theta\right)\right]}{\theta_f + \sin\theta_f}$$



Stresses

$$\frac{\partial v_r}{\partial r} = 0, \quad \frac{1}{r} \frac{\partial v_{\theta}}{\partial \theta} + \frac{v_r}{r} = 0 \implies \tau = \begin{pmatrix} -p & \tau_{r\theta} \\ \tau_{r\theta} & -p \end{pmatrix}$$

Back-arc

$$\tau_{r\theta} = \frac{2\nu\eta}{r} \frac{\left[\theta_b \cos\left(\theta_b - \theta\right) - \sin\theta_b \cos\theta\right]}{\theta_b^2 - \sin^2\theta_b}$$

Fore-arc

$$\tau_{r\theta} = \frac{2\nu\eta}{r} \frac{\cos\theta + \cos\left(\theta_f - \theta\right)}{\theta_f + \sin\theta_f}$$

Figure by MIT OCW.



Figure by MIT OCW.

<u>**Pressure**</u> – no direct equation

But – equilibrium
$$\tau_{ij,j} = 0$$

 $-\frac{\partial p}{\partial r} + \frac{1}{r} \frac{\partial \tau_{r\theta}}{\partial \theta} = 0$
 $-\frac{1}{r} \frac{\partial p}{\partial \theta} + \frac{2}{r} \tau_{r\theta} + \frac{\partial \tau_{r\theta}}{\partial r} = 0$

Back-arc

$$p = -\frac{2\nu\eta}{r} \frac{\left[\theta_b \sin\left(\theta_b - \theta\right) + \sin\theta_b \sin\theta\right]}{\theta_b^2 - \sin^2\theta_b} < 0$$

$$\rightarrow -\frac{2\nu\eta}{r} \frac{\theta_b \sin\theta_b}{\theta_b^2 - \sin^2\theta_b} \text{ at surface } \rightarrow -\frac{2\nu\eta}{r} \frac{\sin^2\theta_b}{\theta_b^2 - \sin^2\theta_b} \text{ on slab}$$

Fore-arc

$$p = \frac{2\nu\eta}{r} \frac{\sin\theta - \sin\left(\theta - \theta_f\right)}{\theta_f + \sin\theta_f} > 0$$

 $\rightarrow \frac{2\nu\eta}{r} \frac{\sin\theta_f}{\theta_f + \sin\theta_f} \text{ at surface and on slab}$

⇒ excess pressure in fore-arc suction in back-arc – tendency to lift slab (and also modify surface topography)



Figure by MIT OCW.

This flow tends to lift slab –

Resisted by

- 1) gravity
- 2) resistance to squeezing material out of wedge [not well posed for ∞ wedge \rightarrow needs ∞ work]

Consider gravity - torque balance



Figure by MIT OCW.



Ridge problem



Figure by MIT OCW.

By symmetry, at $\theta = \frac{\pi}{2}$, $v_{\theta} = 0$, $\tau_{r\theta} = 0$ Let $\psi = r\Theta$ $v_r = \Theta'$ $\tau_{r\theta} = \frac{\eta}{r} (\Theta'' + \Theta)$ $v_{\theta} = -\Theta$ $p = -\frac{\eta}{r} (\Theta''' + \Theta')$ $\nabla^4 \psi = 0$ $\Theta = A \sin \theta + B \cos \theta + C\theta \sin \theta + D\theta \cos \theta$

$$\begin{array}{c|c} \theta = 0 & v_{\theta} = 0 \Rightarrow B = 0 & \theta = \pi/2 & v_{\theta} = 0 \Rightarrow A + (\pi/2)C = 0 \\ v_{r} = v = A + D & \tau_{r\theta} = 0 \Rightarrow D = 0 \\ A = v, \ C = -(2/\pi)v & \tau_{r\theta} = \frac{4\eta v}{\pi r}\cos\theta \\ v_{r} = \frac{2v}{\pi} \left[\left(\frac{\pi}{2} - \theta\right)\cos\theta - \sin\theta \right] & \tau_{r\theta} = \frac{4\eta v}{\pi r}\cos\theta \\ v_{\theta} = \frac{-2v}{\pi} \left(\frac{\pi}{2} - \theta\right)\sin\theta & p = -\frac{4\eta v\sin\theta}{\pi r} \end{array}$$

