### Massachusetts Institute of Technology

## Department of Electrical Engineering and Computer Science 6.245: MULTIVARIABLE CONTROL SYSTEMS

by A. Megretski

# Problem Set 5 (due March 10, 2004)<sup>1</sup>

Problem 5.1

Use KYP Lemma to find (analytically) the set of all  $a \in \mathbf{R}$  such that the Riccati equation

PA + A'P = (C' - PB)(C - B'P),

where (A, B) is controllable, (C, A) is observable, and

$$C(sI - A)^{-1}B = (s + a)^{-1000},$$

has a stabilizing solution P = P'.

#### Problem 5.2

Using the generalized Parrot's theorem, write down an algorithm for finding matrix L which minimizes the largest eigenvalue of

$$M = M(L) = \begin{bmatrix} \alpha & \beta + 2L \\ 2L' + \beta' & \gamma + L'L \end{bmatrix},$$

where  $\alpha = \alpha', \beta$ , and  $\gamma = \gamma'$  are given matrices.

<sup>&</sup>lt;sup>1</sup>Version of March 3, 2004

### Problem 5.3

Use the KYP Lemma to write a MATLAB algorithm for checking that a given stable transfer function G = G(s), available in a state space form, satisfies the condition

$$|G(j\omega)| > 1 \quad \forall \ \omega \in \mathbf{R} \cup \{\infty\}.$$

The algorithm should be exact, provided that the linear algebra operations involved (matrix multiplications, eigenvalue calculations, comparison of real numbers) are performed without numerical errors. In particular, checking that  $|G(j\omega_k)| > 1$  at a finite set of frequencies  $\omega_k$  is not acceptable in this problem<sup>2</sup>.

<sup>&</sup>lt;sup>2</sup>Of course, frequency sampling may be acceptable in many practical applications