

## Recitation 7, February 25, 2010

### Solutions to second order ODEs

#### Solution suggestions

1. Check that both  $x = \cos(\omega t)$  and  $x = \sin(\omega t)$  satisfy the *second order* linear differential equation

$$\ddot{x} + \omega^2 x = 0$$

This equation is called the *harmonic oscillator*.

If  $x = \cos(\omega t)$ , then  $\dot{x} = -\omega \sin(\omega t)$  and  $\ddot{x} = -\omega^2 \cos(\omega t) = -\omega^2 x$ . If  $x = \sin(\omega t)$ , then  $\dot{x} = \omega \cos(\omega t)$  and  $\ddot{x} = -\omega^2 \sin(\omega t) = -\omega^2 x$ .

2. In fact, check that *any* sinusoidal function with circular frequency  $\omega$ ,  $A \cos(\omega t - \phi)$ , satisfies the equation  $\ddot{x} + \omega^2 x = 0$ .

If  $x = A \cos(\omega t - \phi)$ , then  $\dot{x} = -A\omega \sin(\omega t - \phi)$ , and  $\ddot{x} = -A\omega^2 \cos(\omega t - \phi) = -\omega^2 x$ .

3. Among the functions  $x(t) = A \cos(\omega t - \phi)$ , which have  $x(0) = 0$ ? Doesn't this contradict the uniqueness theorem for differential equations?

$x(0) = A \cos \phi$ . When  $A = 0$ , then  $x(t) = 0$  for every  $t$ ; when  $A \neq 0$ ,  $x(0) = 0$  implies  $\cos \phi = 0$ , and hence  $\phi$  can be any odd multiple of  $\pi/2$ , i.e.,  $\phi = \pm\pi/2, \pm3\pi/2, \pm5\pi/2, \dots$ . This does not contradict the uniqueness theorem, because the uniqueness theorem as stated only applies to first order equations.

4. Given numbers  $x_0$  and  $\dot{x}_0$ , can you find a solution to  $\ddot{x} + \omega^2 x = 0$  for which  $x(0) = x_0$  and  $\dot{x}(0) = \dot{x}_0$ ? How many such solutions are there?

Suppose  $x(t) = a \cos(\omega t) + b \sin(\omega t)$ .  $x(0) = a$ , so  $a = x_0$ .  $x'(0) = -a\omega \sin 0 + b\omega \cos 0 = b\omega = \dot{x}_0$ . Then  $b = \dot{x}_0/\omega$ . The solution is then  $x = x_0 \cos(\omega t) + \dot{x}_0 \sin(\omega t)/\omega$ . There is only one such solution.

5. Suppose that  $r$  is a (perhaps complex) constant such that  $e^{rt}$  is a solution to  $\ddot{x} + kx = 0$ . What does  $r$  have to be?

Let  $x = e^{rt}$ . Then  $\dot{x} = r e^{rt}$ ,  $\ddot{x} = r^2 e^{rt}$ , and  $\ddot{x} + kx = (r^2 + k)e^{rt}$ . We want this to be zero, but since  $e^{rt}$  is never zero, it must be  $r^2 = -k$ . Suppose  $k \geq 0$ , then  $r$  must have the form  $\pm i\sqrt{k}$ .

**6.** Find a solution  $x_1$  to  $\ddot{x} - a^2x = 0$  [note the sign!] such that  $x_1(0) = 1$  and  $\dot{x}_1(0) = 0$ . Find another solution  $x_2$  such that  $x_2(0) = 0$  and  $\dot{x}_2(0) = 1$ .

We use a similar approach as we studied  $\ddot{x} + \omega^2x = 0$ . First, notice that both  $x(t) = e^{at}$  and  $x(t) = e^{-at}$  are solutions to  $\ddot{x} - a^2x = 0$ . Then for any constants  $c_1$  and  $c_2$ ,  $x(t) = c_1e^{at} + c_2e^{-at}$  are also solutions to  $\ddot{x} - a^2x = 0$ . Moreover,  $x(0) = c_1 + c_2$ , and  $\dot{x}(0) = a(c_1 - c_2)$ . Assuming  $a \neq 0$ , to get  $x_1(t)$ , we need  $c_1 + c_2 = 1$  and  $a(c_1 - c_2) = 0$ , which implies  $c_1 = c_2 = 1/2$ . So  $x_1(t) = \cosh(at)$ . For  $x_2(t)$ , set  $c_1 + c_2 = 0$  and  $a(c_1 - c_2) = 1$ , so  $c_1 = -c_2 = \frac{1}{2a}$  and  $x_2(t) = \sinh(at)/a$ .

MIT OpenCourseWare  
<http://ocw.mit.edu>

18.03 Differential Equations  
Spring 2010

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.