## Cramer's rule, inverse matrix, and volume

We know a formula for and some properties of the determinant. Now we see how the determinant can be used.

## Formula for $A^{-1}$

We know:

$$
\left[\begin{array}{ll}
a & b \\
c & d
\end{array}\right]^{-1}=\frac{1}{a d-b c}\left[\begin{array}{rr}
d & -b \\
-c & a
\end{array}\right]
$$

Can we get a formula for the inverse of a 3 by 3 or $n$ by $n$ matrix? We expect that $\frac{1}{\operatorname{det} A}$ will be involved, as it is in the 2 by 2 example, and by looking at the cofactor matrix $\left[\begin{array}{rr}d & -c \\ -b & a\end{array}\right]$ we might guess that cofactors will be involved.

In fact:

$$
A^{-1}=\frac{1}{\operatorname{det} A} C^{T}
$$

where $C$ is the matrix of cofactors - please notice the transpose! Cofactors of row one of $A$ go into column 1 of $A^{-1}$, and then we divide by the determinant.

The determinant of $A$ involves products with $n$ terms and the cofactor matrix involves products of $n-1$ terms. $A$ and $\frac{1}{\operatorname{det} A} C^{T}$ might cancel each other. This is much easier to see from our formula for the determinant than when using Gauss-Jordan elimination.

To more formally verify the formula, we'll check that $A C^{T}=(\operatorname{det} A) I$.

$$
A C^{T}=\left[\begin{array}{rcr}
a_{11} & \cdots & a_{1 n} \\
\vdots & \ddots & \vdots \\
a_{n 1} & \cdots & a_{n n}
\end{array}\right]\left[\begin{array}{rrr}
C_{11} & \cdots & C_{n 1} \\
\vdots & \ddots & \vdots \\
C_{1 n} & \cdots & C_{n n}
\end{array}\right] .
$$

The entry in the first row and first column of the product matrix is:

$$
\sum_{j=1}^{n} a_{1 j} C_{j 1}=\operatorname{det} A .
$$

(This is just the cofactor formula for the determinant.) This happens for every entry on the diagonal of $A C^{T}$.

To finish proving that $A C^{T}=(\operatorname{det} A) I$, we just need to check that the offdiagonal entries of $A C^{T}$ are zero. In the two by two case, multiplying the entries in row 1 of $A$ by the entries in column 2 of $C^{T}$ gives $a(-b)+b(a)=0$. This is the determinant of $A_{s}=\left[\begin{array}{ll}a & b \\ a & b\end{array}\right]$. In higher dimensions, the product of the first row of $A$ and the last column of $C^{T}$ equals the determinant of a matrix whose first and last rows are identical. This happens with all the off diagonal matrices, which confirms that $A^{-1}=\frac{1}{\operatorname{det} A} C^{T}$.

This formula helps us answer questions about how the inverse changes when the matrix changes.

## Cramer's Rule for $\mathbf{x}=A^{-1} \mathbf{b}$

We know that if $A \mathbf{x}=\mathbf{b}$ and $A$ is nonsingular, then $\mathbf{x}=A^{-1} \mathbf{b}$. Applying the formula $A^{-1}=C^{T} / \operatorname{det} A$ gives us:

$$
\mathbf{x}=\frac{1}{\operatorname{det} A} C^{T} \mathbf{b}
$$

Cramer's rule gives us another way of looking at this equation. To derive this rule we break $\mathbf{x}$ down into its components. Because the $i^{\prime}$ th component of $C^{T} \mathbf{b}$ is a sum of cofactors times some number, it is the determinant of some matrix $B_{j}$.

$$
x_{j}=\frac{\operatorname{det} B_{j}}{\operatorname{det} A},
$$

where $B_{j}$ is the matrix created by starting with $A$ and then replacing column $j$ with $\mathbf{b}$, so:

$$
\begin{aligned}
& B_{1}=\left[\begin{array}{c}
\text { last } \mathrm{n}-1 \\
\left.\mathbf{b} \begin{array}{c}
\text { columns } \\
\text { of } A
\end{array}\right] \text { and } \\
B_{n}=\left[\begin{array}{c}
\text { first } \mathrm{n}-1 \\
\begin{array}{c}
\text { columns } \\
\text { of } A
\end{array}
\end{array}\right] .
\end{array} \quad . \quad \begin{array}{l}
\text { b }
\end{array}\right] .
\end{aligned}
$$

This agrees with our formula $x_{1}=\frac{\operatorname{det} B_{1}}{\operatorname{det} A}$. When taking the determinant of $B_{1}$ we get a sum whose first term is $b_{1}$ times the cofactor $C_{11}$ of $A$.

Computing inverses using Cramer's rule is usually less efficient than using elimination.

## $|\operatorname{det} A|=$ volume of box

Claim: $|\operatorname{det} A|$ is the volume of the box (parallelepiped) whose edges are the column vectors of $A$. (We could equally well use the row vectors, forming a different box with the same volume.)

If $A=I$, then the box is a unit cube and its volume is 1 . Because this agrees with our claim, we can conclude that the volume obeys determinant property 1.

If $A=Q$ is an orthogonal matrix then the box is a unit cube in a different orientation with volume $1=|\operatorname{det} Q|$. (Because $Q$ is an orthogonal matrix, $Q^{T} Q=I$ and so $\operatorname{det} Q= \pm 1$.)

Swapping two columns of $A$ does not change the volume of the box or (remembering that $\operatorname{det} A=\operatorname{det} A^{T}$ ) the absolute value of the determinant (property 2). If we show that the volume of the box also obeys property 3 we'll have proven $|\operatorname{det} A|$ equals the volume of the box.


Figure 1: The box whose edges are the column vectors of $A$.

If we double the length of one column of $A$, we double the volume of the box formed by its columns. Volume satisfies property 3(a).

Property 3(b) says that the determinant is linear in the rows of the matrix:

$$
\left|\begin{array}{cc}
a+a^{\prime} & b+b^{\prime} \\
c & d
\end{array}\right|=\left|\begin{array}{ll}
a & b \\
c & d
\end{array}\right|+\left|\begin{array}{cc}
a^{\prime} & b^{\prime} \\
c & d
\end{array}\right| .
$$

Figure 2 illustrates why this should be true.


Figure 2: Volume obeys property 3(b).
Although it's not needed for our proof, we can also see that determinants obey property 4 . If two edges of a box are equal, the box flattens out and has no volume.

Important note: If you know the coordinates for the corners of a box, then computing the volume of the box is as easy as calculating a determinant. In particular, the area of a parallelogram with edges $\left[\begin{array}{l}a \\ b\end{array}\right]$ and $\left[\begin{array}{l}c \\ d\end{array}\right]$ is $a d-b c$. The area of a triangle with edges $\left[\begin{array}{l}a \\ b\end{array}\right]$ and $\left[\begin{array}{l}c \\ d\end{array}\right]$ is half the area of that parallelogram, or $\frac{1}{2}(a d-b c)$. The area of a triangle with vertices at $\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)$ and $\left(x_{3}, y_{3}\right)$ is:

$$
\frac{1}{2}\left|\begin{array}{lll}
x_{1} & y_{1} & 1 \\
x_{2} & y_{2} & 1 \\
x_{3} & y_{3} & 1
\end{array}\right|
$$

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### 18.06SC Linear Algebra

Fall 2011

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