### 15.082J and 6.855J and ESD.78J October 26, 2010

## Introduction to Minimum Cost Flows

## Overview of lecture

- Quick review of min cost flow problem
- An application of min cost flows
- The residual network, again
- The cycle canceling algorithm for solving the min cost flow problem
- Reduced costs and optimality conditions


## The Minimum Cost Flow Problem

$\mathbf{u}_{\mathrm{ij}}=$ capacity of $\operatorname{arc}(\mathbf{i}, \mathbf{j})$.
$c_{i j}=$ unit cost of shipping flow from node $i$ to node $j$ on (i,j).
$x_{i j}=$ amount shipped on arc $(\mathrm{i}, \mathrm{j})$

Minimize

$$
\sum_{(i, j) \in A} c_{i j} x_{i j}
$$

$\sum_{\mathrm{j}} \mathrm{x}_{\mathrm{ij}} \quad-\quad \sum_{\mathrm{j}} \mathrm{x}_{\mathrm{ji}}=\mathrm{b}_{\mathrm{i}} \quad$ for all $\mathrm{i} \in \mathbf{N}$.
and $0 \leq x_{i j} \leq u_{i j}$ for all $(i, j) \in A$.

## Find the shortest path from node 1 to node 6



The optimal flow is to send one unit of flow along 1-2-5-6.

This transformation works so long as there are no negative cost cycles in $G$.
(What if there are negative cost cycles?)

## Find the Maximum Flow from s to $t$



# b(i) $=\mathbf{0}$ for all $\mathbf{i}$; <br> add arc ( $\mathrm{t}, \mathrm{s}$ ) with a cost of -1 and large capacity. 

The cost of every other arc is 0 .

The optimal solution in the corresponding minimum cost flow problem will send as much flow in ( $\mathbf{t}, \mathrm{s}$ ) as possible.

## Transshipment Problems

Plants with given production capabilities for a product.

One can ship directly from the plants to retailers, or from plants to warehouses, and then from warehouses to retailers.

There is a given demand for each retailer.
Costs of shipment are given.

What is the minimum cost method for satisfying demands?

## A Network Representation



## The Caterer Problem

Demand for $\mathrm{d}_{\mathrm{i}}$ napkins on day i for $\mathrm{i}=1$ to $\mathbf{7}$ (so, $\mathrm{j} \in[1 . .7]$ ).
Cost of new napkins: a cents each,
2-day laundry: b cents per napkin
1-day laundry: c cents per napkin.
Minimize the cost of meeting demand.

Assumptions:

- there is no initial inventory of napkins
- at the end, no clean napkins remain


## An example with a feasible solution

new napkins: $\$ 10$ Demand:
1 day cleaning \$2
2-day cleaning \$1

M-F 100 napkins,
Sa-Su 125 napkins


## Nodes and Arcs

Node j : Clean napkins on day j
Node j': Dirty napkins on day j
Node 0: Where napkins originate
Node $\mathrm{n}+1$ : Where napkins go to stay dirty

Clean napkins dirty napkins


Clean napkins on day 5 come from

- purchases $(0,5)$
- leftover clean napkins
$(4,5)$
- 2-day laundry $\left(3^{\prime}, 5\right)$
- 1-day laundry (4', 5)

Clean napkins on day 5 go to

- being used $\left(5,5^{\prime}\right)$
- being stored
$(5,6)$


## Nodes and Arcs

Clean napkins

Dirty napkins


Dirty napkins on day 5 come from

- being used on day 5
$\left(5,5^{\prime}\right)$
Dirty napkins on day 5 go to
- never cleaned $(5, n+1)$
- 1-day cleaning $\left(5^{\prime}, 6\right)$
- 2- day cleaning $\left(5^{\prime}, 7\right)$


## The network for the caterer problem



Find a minimum cost circulation such that the flow on $\left(j, j^{\prime}\right)=d_{j}$ on $\operatorname{arcs}\left(j, j\right.$ ') for $j=1$ to $n$. Lower bound = upper bound $=d_{j}$ Arc $(n+1,0): \quad$ each purchased napkin ends up dirty.

## The minimum cost flow problem

- Simplifying assumptions
- Finding a feasible flow
- The residual network
- The cycle canceling algorithm
- Reduced costs and optimality conditions


## Some Assumptions

1. All data is integral. (Needed for some proofs, and some running time analysis).
2. The network is directed and connected
3. $\sum_{i=1 \text { to } n} b(i)=0$.
(Otherwise, there cannot be a feasible solution.)

## Finding a feasible solution

One can find a feasible solution when all lower bounds are $\mathbf{0}$ by solving a single max flow problem.

1. If $b(j)>0$, create $\operatorname{arc}(s, j)$ with $u_{s j}=b(j)$,
2. If $b(j)<0$, create $\operatorname{arc}(j, t)$ with $u_{j t}=-b(j)$


## Finding an artificial feasible solution

One can start with an "artificial" feasible solution with large cost. The flow in these arcs will be 0 at the end.

1. Add nodes $s$ and $t$ with $b(s)=b(t)=0$
2. If $b(j)>0$, create $\operatorname{arc}(j, t)$ with $u_{j t}=b(j)$ and $c_{j t}=0$
3. If $b(j)<0$, create arc ( $s, j)$ with $u_{s j}=-b(j)$ and $\mathrm{c}_{\mathrm{jt}}=0$
4. Add an $\operatorname{arc}(t, s)$ with $u_{t s}=m u_{\text {max }}$ and $c_{t s}=m c_{\text {max }}$


## Finding an artificial feasible solution



Initial solution.

- If $b(j)>0$, then $x_{j t}=b(j) \quad$ (supplies are satisfied)
- If $b(j)<0$, then $x_{s j}=-b(j) \quad$ (demands are satisfied)
- $x_{\text {ts }}=\sum_{b(j)>0} b(j)$
(flow into $t=$ flow out of $t$ )
- $\mathrm{x}_{\mathrm{ij}}=0$ otherwise

In an optimal feasible solution, $\mathrm{x}_{\mathrm{ts}}=0$. There is no flow in any of the artificial arcs)

## Mental Break

Why is the word "ring" part of "boxing ring"?
They used to be round.

How many dimples are in a regulation golf ball?
336

Was "tug of war" ever an Olympic event?
Yes. Between 1900 and 1920.

## Mental Break

Where did karate originate?
In India.

What do the following nicknames for sports teams have in common: the Miami Heat, the Minnesota Wild, the Utah Jazz, the Boston Red Sox, and the Chicago White Sox ?

None of them ends in the letter s.

In which country is kite flying a professional sport?
Thailand.

## The Residual Network G(x)



Suppose $\mathrm{x}_{12}=3$


Reducing the flow in ( $\mathrm{i}, \mathrm{j}$ ) by 1 is equivalent to sending one unit of flow from $j$ to $i$. It reduces the cost by $c_{i j}$.

## Negative cost cycles and augmentations



A residual network $\mathbf{G}(x)$ and its arc costs.

Note: each arc of $\mathrm{G}(\mathrm{x})$ has a cost and a capacity.

Typically, we will only show one of them.

A negative cost cycle refers to a directed cycle in $G(x)$ whose total cost is negative, e.g., 1-3-2-1 and 3-5-4-3

## Negative cost cycles and augmentations



The capacities of the residual network $\mathbf{G}(x)$.

To augment around a cycle $C$ is to send $\delta$ units of flow around C , where $\delta=\min \left\{\mathrm{r}_{\mathrm{ij}}:(\mathrm{i}, \mathrm{j}) \in \mathrm{C}\right\}$

The cycle 1-3-2-1 had negative cost. Its capacity is 15.

## The impact of an augmentation



The capacities of $\mathrm{G}(\mathrm{x})$ before the augmentation.


The capacities after the augmentation.

## Negative Cycle Algorithm

(also known as the cycle canceling algorithm)

## Algorithm NEGATIVE CYCLE;

establish a feasible flow $x$ in the network;
while $\mathbf{G}(x)$ contains a negative cost cycle do
use some algorithm to identify a negative cost cycle C in $\mathrm{G}(\mathrm{x})$;
let $\delta:=\min \left\{\mathrm{r}_{\mathrm{ij}}:(\mathrm{i}, \mathrm{j}) \in \mathrm{C}\right\}$;
augment $\delta$ units of flow in cycle $C$;
update $\mathbf{G}(\mathrm{x})$;

Negative Cycle Algorithm

## More on the Negative Cycle Algorithm

Suppose that all supplies/demands are integral, and capacities are integral. Then the negative cycle algorithm maintains an integral solution at each iteration.

## Finiteness

Theorem. The Negative Cycle Algorithm is finite if all data are finite and integral.

Proof. By flow decomposition, we can express the min cost flow as the sum of $n+m$ paths and cycles. Each path and cycle has a cost bounded by nC , where $\mathrm{C}=\max \left(\left|\mathrm{c}_{\mathrm{ij}}\right|:(\mathrm{i}, \mathrm{j}) \in \mathrm{A}\right)$. The cost of the flow is at most $(\mathrm{nC})(\mathrm{n}+\mathrm{m}) \mathrm{U}$, where U is the largest capacity.

At each iteration of cycle canceling, the cost improves by at least one.

## Optimality

Theorem. The Negative Cycle Algorithm terminates with an optimal flow.

Proof. Consider the final residual network $\mathbf{G}\left(\mathbf{x}^{*}\right)$. Suppose that $x^{*}$ is not optimal. Equivalently, the flow $\mathbf{y}=0$ is not optimal for the circulation problem in $G\left(x^{*}\right)$.

Let $y^{*}$ be a minimum cost circulation in $G\left(x^{*}\right)$. Then $y^{*}$ can be decomposed into flows around cycles. At least one of these cycles (say C) has negative cost. But this contradicts that the algorithm terminated.

## Reduced costs and optimality conditions

## Reduced costs

- recall replacing $c_{i j}-\pi_{i}+\pi_{j}$ for the shortest path problem. The same transformation is very useful for min cost flow algorithms.

Optimality conditions

- Most iterative optimization algorithms stop when "optimality conditions are satisfied". We describe optimality conditions for the min cost flow problem.


## Reduced Costs in $G(x)$

Let $\pi_{i}$ denote the node potential for node $i$.

$$
c_{i j}^{\pi}=c_{i j}-\pi_{i}+\pi_{j}
$$

For unit of flow out of node $i$, subtract $\pi_{i}$ from the cost. For unit of flow into node j , add $\mathrm{m}_{\mathrm{j}}$ to the cost.


## More on Reduced Costs

Lemma. The reduced cost of a cycle is the cost of a cycle.
Proof: $\quad c^{\pi}(C)=\sum_{(i, j) \in C} c_{i j}-\pi_{i}+\pi_{j}=\sum_{(i, j) \in C} c_{i j}=c(C)$


Corollary. Optimizing with respect to reduced costs is equivalent to optimizing with respect to the original costs.

## Optimality Conditions

Theorem. A flow $\mathbf{x}^{*}$ is optimal if and only if there is a vector $\boldsymbol{\pi}^{*}$ so that $\mathbf{c} \boldsymbol{\pi}^{*}{ }_{i j} \geq 0$ for all $(\mathrm{i}, \mathrm{j}) \in \mathrm{G}\left(\mathrm{x}^{\star}\right)$.

Proof. We already know that $\mathbf{x}^{*}$ is optimal if and only if there is no negative cost cycle in $G\left(x^{*}\right)$. It remains to show that there is no negative cycle in $\mathrm{G}\left(\mathrm{x}^{\star}\right)$ if $\exists \boldsymbol{\pi}^{*}$ so that $\mathbf{c} \boldsymbol{\pi}^{*}{ }_{i j} \geq 0$ for all $(\mathrm{i}, \mathrm{j}) \in \mathrm{G}\left(\mathrm{x}^{\star}\right)$.

Suppose first that there is such a vector $\pi^{*}$.

Then the reduced cost of every cycle in $\mathrm{G}\left(\mathrm{x}^{*}\right)$ must be non-negative

## Optimality Conditions

## Proof. Continued.

Suppose now that there is no negative cycle cycle in $G\left(x^{\star}\right)$.

Let $d(i)$ be the shortest path length from node 1 to node $i$ in $\mathrm{G}\left(\mathrm{x}^{\star}\right)$ using original costs. (Assume that such a path exists).

Then for all $(\mathbf{i}, \mathrm{j})$ in $\mathrm{G}\left(\mathrm{x}^{*}\right), \mathrm{d}(\mathrm{j}) \leq \mathrm{d}(\mathrm{i})+\mathrm{c}_{\mathrm{ij}} \forall(\mathrm{i}, \mathrm{j}) \in \mathrm{G}\left(\mathrm{x}^{\star}\right)$ Let $\pi_{i}{ }_{i}=-d(i)$ for all $i$.

Then $\mathrm{c}^{\boldsymbol{\pi}^{*}}{ }_{\mathrm{ij}}=\mathrm{c}_{\mathrm{ij}}+\mathrm{d}(\mathrm{i})-\mathrm{d}(\mathrm{j}) \geq 0$ for all $(\mathrm{i}, \mathrm{j}) \in \mathrm{G}\left(\mathrm{x}^{\star}\right)$.
QED

## Optimality conditions for the original network

If $\mathbf{c}^{\pi^{*}}{ }_{i j} \geq 0$ for all $(\mathrm{i}, \mathrm{j}) \in \mathrm{G}\left(\mathbf{x}^{*}\right)$, what is true about the original network?


Optimality conditions.

1. If $x^{\star}{ }_{i j}=0$, then $(j, i) \notin G\left(x^{\star}\right)$ and $c^{\pi^{*}}{ }_{i j} \geq 0$.
2. If $x_{i j}^{*}=u_{i j}$, then $(i, j) \notin G\left(x^{\star}\right)$ and $\mathbf{C m}^{\boldsymbol{*}}{ }_{\mathrm{ij}} \leq 0$ (so that $\mathrm{c}^{\pi^{*}}{ }_{\mathrm{ji}} \geq 0$ )
3. If $0<\mathbf{x}^{\star}{ }_{\mathrm{ij}}<\mathrm{u}_{\mathrm{ij}}$, then $(\mathrm{i}, \mathrm{j}) \in \mathrm{G}\left(\mathbf{x}^{\star}\right)$ and $(\mathrm{j}, \mathrm{i}) \in \mathrm{G}\left(\mathrm{x}^{\star}\right)$ and $\mathrm{c}^{\pi^{*}}{ }_{\mathrm{ij}}=\mathbf{0}$.

## Optimality conditions again

Optimality conditions 1.

1. If $\mathbf{x}^{\star}{ }_{i j}=0$, then $\mathrm{c}^{\pi^{*}}{ }_{\mathrm{ij}} \geq 0$.
2. If $\mathbf{x}_{\mathrm{ij}}{ }^{=} \mathrm{u}_{\mathrm{ij}}$, then $\mathrm{c}^{\pi^{*}}{ }_{\mathrm{ij}} \leq 0$.
3. If $0<\mathrm{X}_{\mathrm{ij}}^{\star}<\mathrm{u}_{\mathrm{ij}}$, then $\mathrm{c}^{\mathrm{T}^{*}}{ }_{\mathrm{ij}}=\mathbf{0}$.

Opt conditions 1 are equivalent to optimality conditions 2.
Optimality conditions 2.

## Review of Cycle Canceling

Given a flow $x$, we look for negative cost cycles in $G(x)$.

- If we find a negative cost cycle, we sent flow around the cycle
- If we don't find a negative cost cycle, we establish optimality.

It is a very generic algorithm for solving minimum cost flows.

Key subroutine: finding a negative cost cycle. It can be done in different ways.

## How to Find a Negative Cycle

POSSIBILITY 1. Use a shortest path algorithm to determine a negative cost cycle.

POSSIBILITY 2. Find the most negative cost cycle.

POSSIBILITY 3. Augment along the cycle that minimizes
$\operatorname{COST}(\mathrm{C}) /|\mathrm{C}|$. (The cost divided by the number of arcs.)

## Summary

- Some applications of the minimum cost flow problem
- Cycle Canceling Algorithm
- Integrality Property for Minimum Cost Flows
- Optimality Conditions

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